Atlas Copco Generators

QIX 190-540 QAS 80-325 QAC 500-1006



# **USER MANUAL FOR THE**

# **Qc4001 GENERATOR CONTROLLER**



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## 1 <u>General</u>

The Atlas Copco Qc4001 is a protection and control unit for a generator driven by a diesel engine. It will carry out all necessary tasks to control and protect a generator, regardless of the use of the generator. This means that the Atlas Copco Qc4001 can be used for several application types.

The Qc4001 measuring system is true RMS 3-phase measurement of generator voltage, generator current, generator frequency, mains voltage and mains frequency.

This User Manual is based on: Functional Specification 9822 1200 01.

The Functional Specification can be changed without prior notice.

The information contained in this User Manual is to assist you in the installation of your gen-set. If something is not clear, please do not hesitate to contact Atlas Copco for further help.

## 2 Display unit

The display unit used in the Qc4001 communicates and receives power supply via a 9-pole Sub-D plug.

The plug fits directly onto the main unit, so the display can be mounted on the top of the main unit.

If the display is to be used as remote display, a standard computer extension cable with male/female plug can be used for the connection.



## 2.1 Pushbutton functions

There are 16 pushbuttons on the display unit with the following functions:



**ALARM**: Shifts the display 3 lower lines to show the alarm list (up to 30 alarms can be in the list).

**JUMP**: This button enables the customer to enter a channel number selection. The module will jump directly to this channel. Using the JUMP button enables the user to select and display any setting without navigating all the way through the menus (see later).



LEFT: Moves the cursor left for manoeuvring in the menus.



AUTO: Puts the generator in AUTO mode.

**SEMI-AUTO**: Puts the generator in SEMI-AUTO (manual) mode.

**TEST**: Puts the generator in TEST mode.

To enter the TEST mode, the lowest level password needs to be entered.

**VIEW LOG**: Shifts the display 3 lower lines to show the alarm list (up to 150 alarms can be listed). These alarms will be kept in memory when the unit is powered off.

## 2.2 LED functions

## 9 LEDs are used on the display unit.

The colour is green or red or a combination in different situations.



Alarm:	Red LED flashing indicates that unacknowledged alarms are present.
	LED fixed light indicates that ALL alarms are acknowledged.
Power:	Green LED indicates that the auxiliary supply is switched on.
Run:	Green LED indicates that the generator is running.
U/f OK:	Green LED light indicates that voltage/frequency is present and OK.
(GB) ON:	Green LED indicates that the plant contactor is closed.
(MB) ON:	Green LED indicates that the mains contactor is closed.
(MAINS) OK:	LED is green if the mains are present and OK.
	LED is red at a mains failure.
	LED is flashing green when the mains return during the "MAINS OK" delay time.
Auto:	Green LED indicates that AUTO mode is selected.
Semi-Auto:	Green LED indicates that SEMI-AUTO mode is selected.

The main Qc4001 control unit includes 3 LEDs:

Power:	Green LED indicates that the auxiliary supply is switched on.
Self check ok:	Green LED indicates that the unit is OK.
Alarm inhibit:	Green LED fixed light indicates that the inhibit input is ON.

## 3 Standard functions & protections

The Qc4001 measuring system is true RMS 3-phase measurement of generator voltage, generator current, generator frequency, mains voltage and mains frequency.

The Qc4001 module is built up with different extension cards that are mounted into one of the 9 different slots. Some of these cards are mounted as standard, and some as an option.

The Qc4001 has the following control and protection functions as standard:

### 3.1 Engine Protection

The engine alarm extension card has the following configurable inputs and outputs:

- 14...20 mA input for Mains Power Transducer
- 2 configurable 4...20mA inputs
- 3 resistive sensor inputs for Engine Oil Pressure/Coolant Level, Coolant Temperature/Alternator Temperature, Fuel Level
- 1 tacho input
- 9 binary inputs for Access Lock, Running Feedback, Engine Failure, Emergency Stop, 2n<sup>d</sup> Parameter Set, W/L, Remote Start, disable analogue fuel input, Static Battery Charger.

#### 3.2 Alternator Protection

- Over current protection, definite time characteristic
- Reverse power protection, definite time characteristic
- Over- and under voltage (generator and busbar)
- Over- and under frequency (generator and busbar)
- Vector jump
- Df/dt (ROCOF)
- Overload
- Current unbalance
- Voltage asymmetry
- Reactive power (import (excitation loss)/export)

## 3.3 Voltage/var/cos(phi) control

Selectable (via binary inputs or (optional) serial interface) functions:

- Constant voltage (stand-alone)
- Constant reactive power (parallel with mains)
- Constant power factor (parallel with mains)
- Reactive power sharing (parallel with other generators, island operation)

#### 3.4 Analogue controller outputs

- +/-20mA for speed governor
- +/-20mA for voltage/var/cos control

#### 3.5 Load sharing between gen-sets' analogue lines

#### 3.6 Engine communication

Software selectable for:

- MTU MDEC communication
- Detroit Diesel DDEC communication
- Deutz EMR communication
- Volvo EDCIII
- John Deere JDEC communication
- Scania ScaniaDec communication

### 3.7 Configurable I/O extension card

- 13 binary inputs and 4 relay outputs

#### Note: It is possible to configure binary inputs, analogue inputs and binary outputs.

#### **Binary Inputs**

- The text can be edited to a more saying name by using the USW
- Input 10 (terminal 118) can be configured as 'Sprinkler'. When 'Sprinkler' is selected, all alarms and fail classes are overruled. The only alarms the gen-set will react on are 'Emergency Stop' on terminal 117 or a 'Tacho Failure'. Also the gen-set has 7 start attempts before 'Start Failure'.

#### Analogue Inputs

- The text can be edited to a more saying name

#### **Binary Outputs**

- The output can be configured as 'Alarm' relay
- The output can be configured as 'Limit' relay

## 4 Optional functions & protections

As standard 6 slots out of 9 slots contain a dedicated extension card. This means that 3 slots are still free for the optional extension cards. The following optional extension cards are available:

- 4.1 Power Management System (PMS)
- 4.2 <u>Can-open Serial communication</u>
- 4.3 Mod-bus Serial communication
- 4.4 Profi-bus Serial communication

Note that it is only possible to have one of the above options 4.1 - 4.4 on one and the same unit.

- 4.5 Analogue Transducer Output of measured values (2x 4...20mA)
- 4.6 7 Binary Inputs
- 4.7 <u>4 Relay Outputs</u>
- 4.8 <u>4 Analog Inputs (4...20mA)</u>

Note that it is only possible to have one of the above options 4.5 - 4.8 on one and the same unit.

4.9 <u>Ethernet – TCP/IP communication</u>

Integrated Web Server with web pages for plant presentation.

## 5 <u>Hardware</u>

The Qc4001 housing is divided into board slot positions, some of which are standard (nonchangeable) and some intended for options.

The unit is divided like this:

- Slot #1 Power supply and binary I/O 1-28	
- Slot #2 Optional external communication 29-36	i
- Slot #3 Load sharing control/I/O card 37-64	
- Slot #4 Governor control analog outputs 65-72	
- Slot #5 AC measuring 73-89	

- Slot #6 Optional inputs/outputs 90-97
- Slot #7 Engine interface card 98-125
- Slot #8 Engine communication 126-133
- Slot #9 Optional TCP/IP RJ45 conn.

Besides the slots there is an additional board where the communication ports are placed.

- RS232 PC service port

- Display port

An overview of the terminals can be seen on the next page. The slots are positioned in the unit as follows (seen from the top of the unit):

#### Note:

The "Common terminal" is referring to the Power supply (+12/24VDC).

Standard Option Standard Standard Option Standard Standard Option

Standard Standard



Note: For the relay outputs the following terms will be used: NO means Normally Open. NC means Normally Closed. Com. means common terminal for the relay in question.

## 5.1 Slot #1, Power Supply and Binary I/O

Term.	Function	Description	
1	+12/24 VDC	Power supply	
2	0 VDC		
3	NC Status relay	Processor/power supply status supervision	
4	Common terminal for term	inal 3	
5	NO Relay	Central alarm HORN	
6	Common terminal for term	inals 5 and 7	
7	NC Relay	Central alarm HORN	
8	NO Relay	Open mains breaker (open breaker)	
9	Common terminal for term	inals 8 and 10	
10	NC Relay	Open mains breaker (open breaker)	
11	NO Relay	Close mains breaker (synchronising)	
12	Common terminal for term	inals 11 and 13	
13	NC Relay	Close mains breaker (synchronising)	
14	NO Relay	Open generator breaker (deload)	
15	Common terminal for terminals 14 and 16		
16	NC Relay	Open generator breaker (deload)	
17	NO Relay	Close generator breaker (synchronising)	
18	Common terminal for terminals 17 and 19		
19	NC Relay	Close generator breaker (synchronising)	
20	Open collector 1	Transistor out Pulse output 1, kWh counter	
21	Open collector 2	Transistor out Pulse output 2, kvarh counter	
22	Common terminal for terminals 21 and 22		
23	Digital input 1	Optocoupler Alarm inhibit	
24	Digital input 2	Optocoupler Mains breaker open	
25	Digital input 3	Optocoupler Mains breaker closed	
26	Digital input 4	Optocoupler Generator breaker open	
27	Digital input 5	Optocoupler Generator breaker closed	
28	Common terminal for terminals 23 to 27		

The functionality of the alarm inhibit input (terminal 23) is described in the table below:

Alarm inhibit input	ON	OFF
Generator low f	-	ACT
Generator low U	-	ACT
Generator high f	ACT	ACT
Generator high U	ACT	ACT
420 mA input	-	ACT
Binary input	-	ACT
VDO input	-	ACT
Tacho input	-	ACT

ACT = Alarm function is active ON = Input is high

### 5.2 Slot #2, serial communication (optional)

Note: only 1 of the following options can be chosen: Can-open/Mod-bus/Profi-bus/Power Management

- Can-open:

Term.	Function	Description
29	Can-H	The can is based on can-open
30	GND	
31	Can-L	
32	Can-H	
33	GND	
34	Can-L	
35	Not used	
36	Not used	

- Mod-bus:

Term.	Function	Description
29	DATA + (A)	Mod-bus RTU, RS485
30	GND	
31	DATA - (B)	
32	DATA + (A)	
33	GND	
34	DATA - (B)	
35	Not used	
36	Not used	

- Profi-bus:

36

Term.	Function	Description
29	DATA + (B)	Pin 3 on 9 pole sub-D connector
30	GND	Pin 5 on 9 pole sub-D connector
31	DATA - (A)	Pin 8 on 9 pole sub-D connector
32	DATA + (B)	
33	GND	
34	DATA - (A)	
35	Not used	

The serial communication line should be terminated between DATA + and DATA - with a resistor equal to the cable impedance. The terminals 29/32, 30/33 and 31/34 are internally connected on all communication PCBs.

Use shielded twisted pair cable.

Not used

## - Power Management System

Term.	Function	Description
29	Can-H	Internal communication
30	GND	
31	Can-L	
32	Can-H	
22	CND	

- 33 GND
- 34 Can-L
- 35 Not used
- 36 Not used

The communication between Qc4001 units is used for power management purposes. With the Power Management System (PMS), the Can-bus is automatically integrated.

### 5.3 Slot #3, load sharing control, 13 binary inputs and 4 relay outputs

Term.	Function	Description
37	-505 VDC	Active load sharing line I/O
38	Common terminal for load	sharing lines on terminals 37 and 39
39	-505 VDC	Reactive load sharing I/O
40	-10010 VDC	Frequency/active load set-point Input
41	Common terminal for term	inals 40 and 42
42	-10010 VDC	Voltage/var/power factor/reactive load set point In.
43	Binary input 18	2 <sup>nd</sup> Parameter set, not configurable
44	Binary input 19	3 <sup>ra</sup> Parameter set, non configurable
45	Binary input 20	4 <sup>th</sup> Parameter set, non configurable
46	Binary input 21	Configurable
47	Binary input 22	Configurable
48	Binary input 23	Configurable
49	Binary input 24	Configurable
50	Binary input 25	Configurable
51	Binary input 26	Configurable
52	Binary input 27	Configurable
53	Binary input 28	Configurable
54	Binary input 29	Configurable
55	Binary input 30	Configurable
56	Common terminal for terminals 43 to 55	
57	NO Relay 1	Configurable
58	Common terminal for terminal 57	
59	NO Relay 2	Configurable
60	Common terminal for terminal 59	
61	NO Relay 3	Configurable
62	Common terminal for term	inal 61
63	NO Relay 4	Configurable
64	Common terminal for term	inal 63

## 5.4 Slot #4, analogue outputs for governor and AVR control

Term. 65	<i>Function</i> Not used	Description
66	+/-20 mA out	Speed governor set-point output
67	0 Natural	
68	Not used	
69	Not used	
70	+/-20 mA out	AVR voltage set-point output
71	0	
72	Not used	

The analogue current outputs can, if needed, be converted to voltage using a resistor across the terminals (250 will convert the +/-20 mA into +/-5 VDC).

#### 5.5 Slot #5, AC measuring

Term.	Function	Description
73	I L1 s1	Generator current L1 1/5A AC input
74	I L1 s2	
75	I L2 s1	Generator current L2 1/5A AC input
76	I L2 s2	
77	I L3 s1	Generator current L3 1/5A AC input
78	I L3 s2	
79	U L1	Generator voltage L1
80	Not used	
81	U L2	Generator voltage L2
82	Not used	
83	U L3	Generator voltage L3
84	U neutral	Generator voltage neutral
85	U L1	Mains/bus voltage L1
86	Not used	
87	U L2	Mains/bus voltage L2
88	Not used	
89	U L3	Mains/bus voltage L3

Note: Current inputs are galvanically separated. Max. 0.3 VA per phase.

Voltage measurements are for phase-to-phase voltages between 120VAC and 480VAC.

### 5.6 Slot #6, input/output cards (optional)

Note: only 1 of the following options can be chosen: 7 binary inputs /4 relay outputs/ 4 analogue inputs 4...20mA / Analogue transducer output.

- 7 binary inputs:

- Term. Function
- 90 Common for terminals 91 up to 97
- 91 Configurable Binary Input 17
- 92 Configurable Binary Input 16
- 93 Configurable Binary Input 15
- 94 Configurable Binary Input 14
- 95 Configurable Binary Input 13
- 96 Configurable Binary Input 12
- 97 Configurable Binary Input 11

- 4 relay outputs:

- 90 NO Relay 1
- 91 Common for Terminal 90
- 92 NO Relay 2
- 93 Common for Terminal 92
- 94 NO Relay 3
- 95 Common for Terminal 94
- 96 NO Relay 4
- 97 Common for Terminal 96

- 4 analogue inputs 4...20mA:

- Term. Function
- 90 Common for Terminal 91
- 91 Analogue Input 5
- 92 Common for Terminal 93
- 93 Analogue Input 6
- 94 Common for Terminal 95
- 95 Analogue Input 7
- 96 Common for Terminal 97
- 97 Analogue Input 8

- Analogue transducer output:

These outputs are active outputs i.e. they use the internal power supply. The outputs are galvanically separated from each other and the rest of the Qc4001 unit. The individual output can be selected (in display or via Qc4001 Utility Software) to represent any AC measuring value or related values (e.g. power, power factor, frequency etc.).

For actual selection refer to the channel number 4500-4560.

Via software selection the outputs can be selected to be 0...20mA or 4...20mA.

- Term. Function
- 90 Not Used
- 91 Common for Terminal 92
- 92 Analogue Output 1
- 93 Not Used
- 94 Not Used
- 95 Common for Terminal 96
- 96 Analogue Output 2
- 97 Analogue Input 8

### 5.7 Slot #7, engine interface card

The engine interface board is installed in slot #7. It consists of configurable inputs and outputs. The configuration is done through the Qc4001 Utility Software and the default settings can be changed to the relevant settings. To configure the inputs, upload the parameter list from the Qc4001 and select the input to be configured. Then a configuration dialog box appears and the settings can be changed.

The standard title (e.g. 4...20 mA in no. 2) can be changed and the new title will also be shown in the display.

The minimum and maximum values of the 4...20 mA input can be adjusted:

- Value: Alarm value (e.g. 85°C)
- Min.: Value corresponding to 4 mA (e.g. 0°C)
- Max.: Value corresponding to 20 mA (e.g. 100°C)

The inverse proportional function is used when the input has inverse proportionality according to the measured value.

The inputs can be used for a high or low alarm. As a "high alarm" the alarm appears when the measured value is higher than the alarm limit, and as a "low alarm" the alarm appears when the measured values are lower than the alarm limit.

The relay outputs on slot #7 are used for engine control.

- Start
- Stop solenoid
- Start prepare

The binary inputs use 12/24 volt constant signal. They do not use pulse inputs.

Term.	Function	Description/preconfiguration
98	Analogue input	420 mA mains power input
99	Analogue input	GND for terminal 98
100	Analogue input 1	420 mA configurable input
101	Analogue input 1	GND for terminal 100
102	Analogue input 2	420 mA configurable input
103	Analogue input 2	GND for terminal 102
104	Resistive input 1	for VDO sensor
105	Resistive input 2	for VDO sensor
106	Resistive Input 3	for VDO sensor
107	Common ground for terminals 104-106	
108	Tacho Input	0.570VAC
109	Tacho Input	/1010.000Hz
110	Binary Input 31	Remote Start/Stop
111	Binary input 32	W/L
112	Binary input 33	Disable Analogue Fuel Input
113	Binary Input 34	Static Battery Charger
114	Binary input 6	Access lock, not configurable
115	Binary input 7	Running feedback, not configurable
116	Binary input 8	External engine failure, configurable
117	Binary input 9	Emergency stop, not configurable
118	Binary input 10	Sprinkler, not configurable
119	Common terminal for terminals 110-118	
120	NO	Start relay
121	Common terminal for termina	al 120
122	NO	Run relay
123	Common terminal for terminal 122	
124	NO	Preheat relay
125	Common terminal for terminal 124	

The access lock input blocks the display functions, and the settings and parameters cannot be changed. The view windows are still accessible.

## 5.8 Slot #8, engine communication

Term.	Function	Description
126	Not used	
127	Not used	
128	Can-L	
129	GND	
130	Can-H	
131	Can-L	
132	GND	
133	Can-H	

Can-communication is possible with following engine electronics:

- MTU MDEC
- Detroit Diesel DDEC
- Deutz EMR
- Volvo EDCIII
- John Deere JDEC
- Scania ScaniaDec

The engine electronics' type is selectable through the Qc4001 Utility Software, so that the same hardware can be used for all.

## 6 Languages

The default language (= Master language) used in the Qc4001 is English.

Other available languages are:

- Danish
- Dutch
- Finnish
- French
- German
- Italian
- Norwegian
- Portuguese
- Spanish
- Swedish
- 1 extra language

It is possible for qualified Atlas Copco personnel to edit and/or add text and/or languages through the 'Qc4001 Utility Software'.

Only the Master language English text is non-editable.

For the other languages, empty 'textcells' will be foreseen where the translations can be filled in by qualified Atlas Copco personnel.

With the current type of LCDisplay, it is not possible to display other than Roman characters. For other languages please contact Atlas Copco.

## 7 Standard Modes

The Qc4001 is a protection and control unit for a generator driven by a diesel engine. It will carry out all necessary tasks to control and protect a gen-set, regardless of the use of the generator. This means that the Qc4001 can be used for several application types such as described in chapter 10.

It is possible to operate the Qc4001 in three modes. The required mode can be selected via a dedicated pushbutton.

## 7.1 <u>AUTO mode</u>

The Qc4001 controls the gen-set and the circuit breakers (generator breaker GB and mains breaker MB) automatically according to the operational state.

## 7.2 SEMI-AUTO mode

Manual control and activation of the sequences with the buttons on the LCDisplay. The generator can be started/stopped manually.

The breakers can be closed/opened manually, but the module will check automatically synchronizing sequences.

## 7.3 <u>Test mode</u>

In this mode it is possible to enable/disable the synchronising feature.

When enabled:	<ul> <li>the gen-set will start-up</li> <li>the generator breaker will close after synchronizing</li> <li>the gen-set will take a defined load for a defined period</li> <li>the generator breaker will open</li> <li>the gen-set will cool down for a defined period</li> <li>the generator will stop.</li> </ul>
When disabled:	<ul> <li>the gen-set will start-up</li> <li>the circuit breaker remains open</li> <li>the gen-set will run with no load for a defined period</li> <li>the gen-set stops.</li> </ul>

The percentage of nominal load and running time can be programmed. To go into the TEST mode, the lowest level password needs to be entered.

## 8 Standard Applications

It is possible to select 5 different applications (via display or configurator software).

## 8.1 AMF function

This application is only possible in combination with the AUTO mode. If the SEMI-AUTO mode is selected, the AMF operation will NOT function !!

Installation with the Mains.

- Automatic starting of the gen-set
- Operation of the mains breaker MB and generator breaker GB
- Back synchronising of gen-set to mains when the mains returns
- Stopping of the gen-set

## 8.2 Peak Shaving

This application is possible in combination with the AUTO mode or SEMI-AUTO mode. Installation with the Mains.

An optional Power Transducer is required.

- Automatic starting of the gen-set
- Operation of the mains breaker MB and generator breaker GB
- Load control
- Stopping of the gen-set

#### 8.3 Island Mode

This application is possible in combination with SEMI-AUTO mode or AUTO mode with internal real time clock timer.

Installation is stand alone, never with the Mains.

- Operation of generator breaker GB.

#### 8.4 Fixed Power

This application is possible in combination with SEMI-AUTO mode or AUTO mode with internal real time clock timer.

Installation is stand alone or with the Mains.

- Operation of generator breaker GB

## 8.5 Load Take Over

This application is possible in combination with SEMI-AUTO mode or AUTO mode with internal real time clock timer.

Installation is stand alone or with the Mains.

- Operation of the mains and generator breaker GB

### 8.6 Power Management System

This application is only possible in combination with the AUTO mode. If the SEMI-AUTO mode is selected, the PMS operation will NOT function !! An optional PMS circuit board inside the Qc4001 controller is required. This option cannot be added afterwards.

Installations are possible with stand alone generators or with the Mains (extra Qc4001 Mains is then needed):

- Operation of the generator breaker GB and Mains & Tie breaker
- Automatic start/stop function with multiple gensets depending on the load demand.

## 9 Single Genset use / Multi Genset use

Depending on the amount of generators in the installation, the customer can select between 5 or 6 applications:

### 9.1 Single Gen-set use

Only 1 generator in the installation. Installation can be stand alone or with the Mains.

### 9.2 Multi gen-set use

More than 1 generator in the installation. In practice up to 16 gen-sets can be installed in parallel. Installation can be stand alone or with the Mains.

## 10 Application examples

10.1 <u>Automatic Mains Failure application with Single gen-set installation and with Back-</u> syncronizing of the mains breaker MB

When the Qc4001 is operating in automatic mains failure operation, the following sequence will be run through in a mains failure situation:



The mains failure must be present in the period "FAIL DELAY" before the MB is opened. The timer "FAIL DELAY" will be reset each time when the mains is restored.

When the mains is restored the following sequence is run through:



The mains must have been present in the period "MAINS OK DELAY" before the MB synchronises.

When the gen-set is running it will control the frequency and voltage to the nominal set point.

## 10.2 Peak Shaving operation with Single gen-set installation

When the Qc4001 is operating in peak shaving operation, the following sequence will be run through when the generator is in standby and the imported load increases above the configured limit:



When the load decreases below the stop gen-set limit, the following sequence is run through:



When the gen-set is running it will be loaded between the minimum load limit (e.g. 5%) and the maximum nominal generator load.

## 11 Wirings



#### 11.1 Wiring for AMF, peak shaving, fixed power and load take over application

This drawing gives only a rough overview on the wiring. For details please see the correct circuit diagrams of the machine.

#### 11.2 Wiring for Island and PMS mode application



This drawing gives only a rough overview on the wiring. For details please see the correct circuit diagrams of the machine.

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On the circuit diagrams you will find a terminal block (X25) where all the necessary connections have to be made. The circuit diagram for QAC gen-sets is 9822 0952 54.

Below you see a detail of circuit diagram 9822 0990 52 for QIX gen-sets. Depending on the application the user has to connect the following wires:

- Mains sensing wires on X25.3 / X25.4 / X25.5
- Remote start signal on X25.9 / X25.10
- Mains breaker feedback wires on X25.11 / X25.12
- Mains breaker control wires on X25.13 / X25.14 / X25.15 / X25.16
- Mains power signal (from optional Power Transducer) on X25.21 / X25.22
- Active and reactive load sharing lines on X30.1 / X30.2 / X30.3 / X31.1 / X31.2 / X31.3

Important notes:

- Remove link between X25.10 / X25.11 when NOT running in Island Mode. The Qc4001 module always needs some feedback from the Mains Breaker MB. If you are in Island mode, then there is no mains breaker in the system. In this case we simulate the 'mains breaker open' signal with a bridge.
- Remove link between X25.17 / X25.19 for no droop operation. This is valid for the QIX gen-sets with EMR control. In parallel operation with other gen-sets or with mains, you need a frequency droop.



## 11.3 Load sharing lines

Even though screened cable is not needed, it is recommended if the cable run is longer than 5 m between units.



### Remark :

When the option PMS is installed these load sharing cables are **not** needed. The loads are shared through the PMS communication cable.

### 11.4 Binary inputs

All binary inputs are 12/24 VDC bi-directional optocoupler. The binary inputs use fixed signals. They do not use pulse signals.

#### 11.5 Analogue inputs (external set-points)

The set-point inputs are passive, i.e. an external power source is needed. This can be an active output from e.g. a PLC, or a potentiometer can be used.

#### 11.6 Optocoupler outputs for external counter

The kWh counter (terminals 20-22) and kvarh counter (terminals 21-22) outputs are low-power outputs.

## 11.7 Display cable

A standard computer extension cable can be used (9-pole SUB-D male/female plugs) or a cable can be tailored:

- Wires min. 0.22 mm<sup>2</sup>
- Max. cable length 6 m



Cable types: Belden 9540, BICC H8146, Brand Rex BE57540 or equivalent.

## 11.8 Serial cable for PC

A standard computer null-modem cable can be used (9-pole SUB-D female/female plugs) or a cable can be tailored.



Connect shield to plug metallic casing. If non-metalleic casing is used, leave shield un-connected.

## 12 Applications details for the Qc4001

This chapter shows the correct application configuration for the different use of the Qc4001. The following application configurations are possible:

Single gen-set	AMF operation	AUTO mode
		(SEMI-AUTO mode)*
	Island mode	AUTO mode
		SEMI-AUTO mode
	Peak shaving	AUTO mode
		SEMI-AUTO mode
	Fixed Power	AUTO mode
		SEMI-AUTO mode
	Load Take Over	AUTO mode
		SEMI-AUTO mode
Multi gen-sets	AMF operation	AUTO mode
		(SEMI-AUTO mode)*
	Island mode	AUTO mode
		SEMI-AUTO mode
	Peak shaving	AUTO mode
		SEMI-AUTO mode
	Fixed Power	AUTO mode
		SEMI-AUTO mode
	Load Take Over	AUTO mode
		SEMI-AUTO mode
	Power Management System	AUTO mode
		(SEMI-AUTO mode)*

()\* = the AMF and PMS operation will not function properly, when SEMI-AUTO mode is selected!

It is possible to use the Qc4001 for one of these purposes, or for peak shaving/fixed power/ load take over in combination with AMF.

The correct configuration can be set through the Qc4001 Utility Software or via the setup menu on the LCDisplay.

From each of the above applications the module can jump into the **Test mode**, by pushing the dedicated Test button on the LCDisplay. The gen-set will follow the defined Test sequences and afterwards the gen-set will return in its previous application, always in combination with the AUTO mode.

## 12.1 Single running gen-set

### 12.1.1 AMF operation

When the mains goes outside the user-defined voltage (over and under) or frequency (over and under) for a certain user-defined time, the mains will be disconnected and the gen-set will be started to take over the load.

When the mains is restored within the user-defined limits for a certain user-defined time, the gen-set will synchronise to the mains and deload the gen-set according a user defined ramp before disconnecting the gen-set (only if back-synchronisation feature is enabled) The gen-set will then go into cool down and stop.

The generator is running in a system with only short simultaneous connection to other systems.

It is possible to enable/disable the back synchronisation feature.



Related customer settings:

- Check that the module is in AUTO mode
- Gen-set mode (=application)
- Cool down setting
- Mains V failure
- Mains Hz failure
- Back synchronisation setting of Mains breaker

Related customer wirings:

- Mains sensing lines L1 / L2 / L3.

- Wires for control and feedback of the Mains breaker.

For details on all setpoints, see the setpoint list. For details on the wirings, see the circuit diagram. pushbutton on display channel 4320 channel 4400 channel 4420 channel 4430 channel 4440
## 12.1.2 Island operation

In combination with SEMI-AUTO mode: The gen-set can be started/stopped wih a local start command. The breaker can be closed/opened with a local command (= LOCAL START).

In combination with AUTO mode: The gen-set can be started/stopped with a remote start command (= REMOTE START).

This can be a command through a signal from the internal real time clock.

This can be a command through a binary input. When an external hard-wired switch (connected to this dedicated input) is closed, the unit will start up and the generator breaker will be closed. When this external switch is opened again, the unit will open the generator circuit breaker and stop.

The generator is running in a system without simultaneous connection to other systems.



Related customer settings:

- Select the correct mode (Semi-auto/Auto)
- Gen-set mode (=application)
- Cool down setting
- Start command through internal real time clock
- Stop command through internal real time clock

Related customer wirings:

- Remote Start switch towards the dedicated binary input

For details on all setpoints, see the setpoint list. For details on the wirings, see the circuit diagram. pushbutton on display channel 4320 channel 4400 channel 4710 - 4780 channel 4710 - 4780

## 12.1.3 Peak Shaving application

In combination with AUTO mode:

The gen-set will start up when the mains imported power (measured through an optional Power Transducer PT) exceeds a user-defined level. The gen-set will synchronise with the bus, and will take load according a user-defined ramp until the user-defined allowable mains imported power level is reached.

When the mains imported power decreases below the user-defined mains imported power level for a user-definable time, the gen-set will deload according a user-defined ramp and disconnect from the bus. Then the gen-set will go into cooldown.

It is possible to define two levels of max. mains imported power: 'day' level and 'night' level.

In combination with SEMI-AUTO mode:

The gen-set starts up once a local start command is given. The gen-set breaker closes once the local command is given, and the synchronisation is done. The gen-set will take load only if the mains imported power exceeds a user-defined level.

The gen-set breaker can be opened and the gen-set stopped with a local command.

The generator is running in a system with long simultaneous connection to other systems.

It is possible to enable/disable AMF as a second application when the gen-set is in the peak shaving application. With AMF enabled, the gen-set will always guard the mains and will act as an AMF unit when not active as a peak shaving gen-set. It is possible to enable/disable the back synchronisation feature.



Related customer settings:

- Select the correct mode (Semi-auto/Auto)
- Power ramp up / ramp down
- Mains imported power level
- Daytime period
- Gen-set mode (=application)
- Cool down setting
- Back synchronisation setting of Mains breaker
- Enable/disable AMF as 2<sup>nd</sup> application

pushbutton on display channel 2110 - 2120 channel 3010 channel 3020 channel 4320 channel 4400 channel 4440 channel 4440 Related customer wirings:

- Power Transducer lines
- Wires for control and feedback of the Mains breaker

For details on all setpoints, see the setpoint list. For details on the wirings, see the circuit diagram For more information on the Power Transducer option, please contact Atlas Copco.

## 12.1.4 Fixed Power

In combination with SEMI-AUTO mode:

The gen-set will start up on a local command. The gen-set will synchronise with the mains, it will connect with the bus and it will take load according to a user-defined level and according a user-defined ramp.

Stopping on a local command will deload the gen-set according a user-defined ramp and disconnect the gen-set from the bus. Then the gen-set will go into cooldown and stop.

In combination with AUTO mode:

The gen-set will go through the same sequences once a remote command is given. This can be a command through a signal from the internal real time clock.

Or this can be a command through a binary input. When an external hard-wired switch (connected to this dedicated input) is closed, the unit will start up and the generator breaker will be closed. When this external switch is opened again, the unit will open the generator circuit breaker and stop.

It is possible to enable/disable AMF as a second application when the gen-set is in fixe power application. With AMF enabled, the gen-set will always guard the mains and will act as an AMF unit when not active as a fixed power gen-set.

It is possible to enable/disable the back synchronisation feature.

The generator is running in a system with long simultaneous connection to other systems.



Related customer settings:

- Select the correct mode (Semi-auto/Auto)
- Power ramp up / ramp down
- Fixed Power setpoint
- Gen-set mode (=application)
- Cool down setting
- Back synchronisation setting of Mains breaker
- Enable/disable AMF as 2<sup>nd</sup> application
- Start command through internal real time clock
- Stop command through internal real time clock

pushbutton on display channel 2110 - 2120 channel 3080 channel 4320 channel 4400 channel 4440 channel 4440 channel 4710 - 4780 channel 4710 - 4780

Related customer wirings:

- Remote Start switch towards the dedicated binary input.
- Wires for control and feedback of the Mains breaker.

For details on all setpoints, see the setpoint list. For details on the wirings, see the circuit diagram.

12.1.5 Load Take Over

In combination with SEMI-AUTO mode:

The gen-set will start up on a local command. The gen-set will synchronise with the mains, it will connect with the bus, and it will take over the load according a user-defined ramp and disconnect the mains. To know if the load is completely taken over from the mains, an optional Power Transducer (PT) is necessary.

After a local stop command, the gen-set will synchronise again to mains, connect the bus to mains, deload the gen-set according a user-defined ramp and disconnect the gen-set from the bus. Then the gen-set will go into cooldown and stop.

In combination with AUTO mode:

The gen-set will go through the same sequences once a remote command is given. This can be a command through a signal from the internal real time clock. Or this can be a command through a binary input.

It is possible to enable/disable AMF as a second application when the gen-set is in the Load Take Over application. With AMF enabled, the gen-set will always guard the mains and will act as an AMF unit when not active as a Load Take Over gen-set. It is possible to enable/disable the back synchronisation feature.

The generator is running in a system with short simultaneous connection to other systems.



Related customer settings:

- Select the correct mode (Semi-auto/Auto)	pushbutton on display
- Power ramp up / ramp down	channel 2110 - 2120
<ul> <li>Gen-set mode (=application)</li> </ul>	channel 4320
- Cool down setting	channel 4400
<ul> <li>Back synchronisation setting of Mains breaker</li> </ul>	channel 4440
<ul> <li>Enable/disable AMF as 2<sup>nd</sup> application</li> </ul>	channel 4440
<ul> <li>Start command through internal real time clock</li> </ul>	channel 4710 - 4780
- Stop command through internal real time clock	channel 4710 - 4780

Related customer wirings:

- Remote Start switch towards the dedicated binary input
- Wires for control and feedback of the Mains breaker
- Wires from the optional Power Transducer

For details on all setpoints, see the setpoint list.

For details on the wirings, see the circuit diagram.

For more information on the Power Transducer option, please contact Atlas Copco.

## 12.2 Multi running gen-sets

## 12.2.1 AMF operation (optional)

It is possible to have an optional power management system (PMS) that allows communication between the Qc4001 modules over CAN-bus. It has fully intelligent system which will start up all gen-sets in case of a mains failure, and then stops and starts gen-sets according to the actual load and according to each gen-set's status.

It is possible to do this kind of intelligent load sharing between up to 16 Qc4001 controllers (all equipped with this PMS option). This PMS option needs to be installed from the factory and can not be added in the field !

The generators are running in a system with only short simultaneous connection to other systems. For the correct working all the generator Qc4001 controllers need to be programmed in AMF – AUTO mode and the Qc4001 mains controller has to put in AMF – AUTO mode. An complete overview on the parameters that needs to be programmed in both controllers you can find below.



Related customer settings Qc4001 controller genset :

- Check that the module is in AUTO mode
- Gen-set mode (=application)
- Cool down setting
- Application
- Int. Communication ID
- PMS configuration
- Priority Select
- Stop Noncon. Gen-sets
- Running hours priority selection
- Manual priority selection
- Number of ID's
- Load dependent start
- Load dedendent stop

pushbutton on display channel 4320 channel 4400 channel 5000 channel 3110 channel 3100 channel 3120 channel 3220 channel 3220 channel 3160 - 3180 channel 3130 - 3150 channel 3050 channel 3060 Extra related customer settings Qc4001 Mains controller :

- Mains V failure
  Mains Hz failure
  Back synchronisation setting of Mains breaker
- Power capacity set-point
- Tie breaker
- Application

## Remark :

The Qc4001 controller of the generators and the Qc4001 mains controller are **NOT** the same controllers. It is not possible to mutual exchange the 2 controllers !

Related customer wirings:

- Mains sensing lines L1 / L2 / L3.
- Wires for control and feedback of the Mains and Tie breaker.
- PMS communication lines.

For more details on related customer settings, see the setpoint list. For more details on related customer wirings, see circuit diagram. For more details on the PMS option, see 12.2.6.

## 12.2.2 Island operation

In combination with SEMI-AUTO mode:

Starting up and loading generators can be done through local commands on the LCDisplays of each unit. For each extra generator that is started, the breaker will close once the local command is given and the synchronisation is done.

In combination with AUTO mode:

Starting up and loading generators can be done through a remote command. This can be a command through a signal from the internal real time clock. Or this can be a command through a binary input.

The load sharing will be done through the analogue load sharing lines.

It is possible to do load sharing between up to 8 gen-sets.

This 'analogue' load sharing is compatible with the Barber Colman Pow-R-Con. This means that old gen-sets can be parallelled with new gen-sets.

Optional it is possible to have a power management system (PMS) which allows communication between the Qc4001 modules over CAN-bus and to have a fully intelligent system which can determine which gen-sets to start and stop, according to the actual load and to each gen-set's status. It is possible to do this kind of intelligent load sharing between up to16 Qc4001 controllers (all equipped with this PMS option).

channel 4420 channel 4430 channel 4440 channel 3250 channel 3260 channel 5000

## Remark :

When paralleling generators with PMS, it is no longer necessary to use the analogue load sharing lines. This will be done through the PMS communication lines.

The generators are running in a system without simultaneous connection to other systems.



Related customer settings:

- Select the correct mode (Semi-auto/Auto)
- Gen-set mode (=application)
- Cool down setting
- Start command through internal real time clock
- Stop command through internal real time clock

Extra related settings if the PMS option is added :

- Application
- Int. Communication ID
- PMS configuration
- Priority Select
- Stop Noncon. Gen-sets
- Running hours priority selection
- Manual priority selection
- Number of ID's
- Load dependent start
- Load dedendent stop

pushbutton on display channel 4320 channel 4400 channel 4710 - 4780 channel 4710 - 4780

channel 5000 channel 3110 channel 3120 channel 3240 channel 3220 channel 3160 - 3180 channel 3130 - 3150 channel 3050 channel 3060 Related customer wirings:

- Remote Start switch towards the dedicated binary input
- PMS communication lines

For more details on related customer settings, see the setpoint list. For more details on related customer wirings, see circuit diagram. For more details on the PMS option, see 12.2.6.

## 12.2.3 Peak Shaving (optional)

It is possible to have an optional power management system (PMS) which allows communication between the Qc4001 modules over CAN-bus and to have a fully intelligent system which will start and stop the necessary gen-set(s) to limit the imported mains power (measured through an optional Qc4001 Mains controller module) according the user-defined level.

It is possible to define 2 levels of max mains imported power: 'day' level and 'night' level. It is possible to do this kind of intelligent peak shaving with up to 16 Qc4001 controllers (all equipped with this PMS option).

The generators are running in a system with long simultaneous connection to other systems.

It is possible to enable/disable AMF as a second application when the gen-sets are in this peak shaving application.

With AMF enabled, the gen-sets will always guard the mains and will act as AMF units when not active as peak shaving gen-sets (extra Tie breaker is needed; see 12.2.1).

It is possible to enable/disable the back synchronisation feature.



Related customer settings:

- Select the correct mode (Semi-auto/Auto)
- Power ramp up / ramp down
- Mains imported power level
- Daytime period
- Gen-set mode (=application)
- Cool down setting
- Back synchronisation setting of Mains breaker
- Enable/disable AMF as 2<sup>nd</sup> application
- Application
- Int. Communication ID
- PMS configuration
- Priority Select
- Stop Noncon. Gen-sets
- Running hours priority selection
- Manual priority selection
- Number of ID's
- Load dependent start
- Load dedendent stop

pushbutton on display channel 2110 - 2120 channel 3010 channel 3020 channel 4320 channel 4400 channel 4440 channel 4440 channel 5000 channel 3110 channel 3100 channel 3120 channel 3240 channel 3220 channel 3160 - 3180 channel 3130 - 3150 channel 3050 channel 3060

Related customer wirings:

- Mains sensing lines L1 / L2 / L3
- Wires for control and feedback of the Mains breaker
- PMS communication lines

For more details on related customer settings, see the setpoint list. For more details on related customer wirings, see circuit diagram. For more details on the PMS option, see 12.2.6.

## 12.2.4 Fixed Power (optional)

It is possible to have an optional power management system (PMS) which allows communication between the Qc4001 modules over CAN-bus and to have a fully intelligent system which will start up the necessary gen-set(s) when a start signal is given, synchronise the gen-set(s) with the mains, connect the gen-set(s) with the bus and load according a user-defined ramp to meet the user-defined fixed load. When a stop signal is given, the gen-set(s) will be deloaded according a user-defined ramp and they will be disconnected from the bus. The gen-set(s) will go into cooldown and stop.

The start and stop signals can be local commands (in combination with SEMI-AUTO mode), or remote commands from the binary input or from the internal real time clock (in combination with AUTO mode).

It is possible to do this kind of intelligent fixed loading with up to 16 QC4001 controllers (all equipped with this PMS option).

The generators are running in a system with long simultaneous connection to other systems.

It is possible to enable/disable AMF as a second application when the gen-sets are in this fixed power application. With AMF enabled, the gen-sets will always guard the mains and will act as AMF units when not active as a fixed power gen-sets (extra Tie breaker is needed; see 12.2.1).

It is possible to enable/disable the back synchronisation feature.



Related customer settings:

- Select the correct mode (Semi-auto/Auto)
- Power ramp up / ramp down
- Fixed Power setpoint
- Gen-set mode (=application)
- Cool down setting
- Back synchronisation setting of Mains breaker
- Enable/disable AMF as 2<sup>nd</sup> application
- Start command through internal real time clock
- Stop command through internal real time clock
- Application
- Int. Communication ID
- PMS configuration
- Priority Select
- Stop Noncon. Gen-sets
- Running hours priority selection
- Manual priority selection
- Number of ID's
- Load dependent start
- Load dedendent stop

Related customer wirings:

- Mains sensing lines L1 / L2 / L3
- Remote Start switch towards the dedicated binary input
- Wires for control and feedback of the Mains breaker
- PMS communication lines

pushbutton on display channel 2110 - 2120 channel 3080 channel 4320 channel 4400 channel 4440 channel 4440 channel 4710 - 4780 channel 4710 - 4780 channel 5000 channel 3110 channel 3100 channel 3120 channel 3240 channel 3220 channel 3160 - 3180 channel 3130 - 3150 channel 3050 channel 3060

For more details on related customer settings, see the setpoint list. For more details on related customer wirings, see circuit diagram. For more details on the PMS option, see 12.2.6.

## 12.2.5 Load Take Over (optional)

It is possible to have an optional power management system (PMS) which allows communication between the Qc4001 modules over CAN-bus and to have a fully intelligent system which will start the necessary gen-set(s) on a local command or remote command, synchronise the gen-set(s) to mains, connect to the bus, take over the load according a user defined ramp and disconnect mains.

This intelligent system will start and stop gen-sets to meet the actual load.

After a local command or remote stop command, the gen-set(s) will synchronise to mains, connect the bus to mains, deload the gen-set(s) according a user defined ramp and disconnect the gen-set from the bus. Then the gen-set(s) will go into cooldown and stop. It is possible to do this kind of intelligent load take over with up to 16 Qc4001 controllers (all equipped with this PMS option).

The local commands can be given when the module is in SEMI-AUTO mode. The remote commands can be given when the module is in AUTO mode. This can be through the binary input or through a signal from the internal real time clock.

The generator is running in a system with short simultaneous connection to other systems.

It is possible to enable/disable AMF as a second application when the gen-sets are in this Load Take Over application. With AMF enabled, the gen-sets will always guard the mains and will act as AMF units when not active as Load Take Over gen-sets (extra Tie breaker is needed; see 12.2.1).

It is possible to enable/disable the back synchronisation feature.



Related customer settings:

- Select the correct mode (Semi-auto/Auto)
- Power ramp up / ramp down
- Gen-set mode (=application)
- Cool down setting
- Back synchronisation setting of Mains breaker
   Enable/disable AMF as 2<sup>nd</sup> application
- Start command through internal real time clock
- Stop command through internal real time clock
- Application
- Int. Communication ID
- PMS configuration
- Priority Select
- Stop Noncon. Gen-sets
- Running hours priority selection
- Manual priority selection
- Number of ID's
- Load dependent start
- Load dependent stop

Related customer wirings:

- Mains sensing lines L1 / L2 / L3
- Remote Start switch towards the dedicated binary input
- Wires for control and feedback of the Mains breaker
- PMS communication lines

pushbutton on display channel 2110 - 2120 channel 4320 channel 4400 channel 4440 channel 4440 channel 4710 - 4780 channel 4710 - 4780 channel 5000 channel 3110 channel 3100 channel 3120 channel 3240 channel 3220 channel 3160 - 3180 channel 3130 - 3150 channel 3050

channel 3060

For more details on related customer settings, see the setpoint list. For more details on related customer wirings, see circuit diagram. For more details on the PMS option, see 12.2.6.

## 12.2.6 Power Management System (optional)

PMS (= Power Management System) is a system that will automatically start & stop generators based on the actual load dependency. This will be done through a PMS communication between the different units connected.

PMS applications are always in combination with AUTO mode. The Qc4001 controllers from the gensets need to be programmed as PMS in AUTO mode. When a Qc Mains controller is installed this needs to be programmed in the application that is required (AMF, LTO, Fixed power) and AUTO mode.

## Warning:

By programming the parameters in AUTO mode, the generator can start up immediately. It is recommended to place the generator in SEMI-AUTO mode while programming all the PMS parameters !

In an application with PMS it is important to program correctly the Start & Stop signals between the different generators because of the following reasons:

- The maximum load step needs to be programmed in the Qc4001 controllers. This never may exceeds the power reserve of the running generators. Otherwise the gensets will go in overload with a sudden max. load increase before the next generator is started up and connected to the busbar.
- To prevent the gensets to run in a start stop loop.

The start signal is the value of the maximum required load step The stop signal is the value when the generator should be stopped automatically.

Example : Installation with 3 gensets : G1 = 300 kW; G2 = 200 kW; G3 = 200 kW

Start signal is set at 90kW (Maximum load step < 90kW)</li>
 Start signal if :

Total Power needed > (Total available power of running gensets –setpoint start signal)

Only G1 is running; at 210kW load (300kW – 90kW) => **G2 will be started** G1 & G2 are running; at 410kW load (200kW + 300kW –90kW) => **G3 will be started**  - Stop signal is set at 100kW and priority is set as (high) G1 > G2 > G3 (low) Stop signal if :

Total Power needed < (Total available power of running gensets – Power of generator with lowest priority – setpoint stop signal)

G1&G2&G3 are running; at 400kW (700kW – 200kW –100kW) => **G3 will be stopped** G1&G3 are running; at 200kW (500kW – 200kW – 100kW) => **G2 will be stopped** 

The priority on starting & stopping the generators can be chosen on priority settings or on the amount of running hours. In manual mode the start & stop sequence is determent by the chosen priority between the generators. The generator with the lowest priority will start as the latest genset and will stop as first. If running hours are chosen as priority the start & stop sequence will be defined based on the actual running hours of the different generators. The lowest running hours will get the highest priority.

## Remark :

When paralleling generators with PMS, it is no longer necessary to use the analogue load sharing lines. This will be done through the PMS communication lines. Use a screened CAN communication cable with a maximum total distance of 200 meters. Do not connect the cable screen to the ground ! Use a 120 Ohm resistor at both end controllers of the PMS as described in the drawings below.

The connections between the generators Qc4001 controllers (without the Qc mains controller) :



The connections for PMS between the generator and the Qc mains controller :



## 13 Remote control via www (optional)

It is possible to communicate with the Qc4001 through the world wide web or local intranet. To be able to use this feature, one Qc4001 must be installed with the optional TCP/IP hardware, and all Qc4001 modules must be installed with the optional Can-bus communication (standard when PMS option installed).

The communication with the world wide web is done through the TCP/IP unit.

This unit communicates through fieldbus with the other units in the system.

The web pages show the installation with the gen-sets, the breakers and the Qc4001 units.

Clicking on the icons on the screen gives access to the following:

- Status: Screen showing the alarms and the status of all control inputs.
- Messages: Creates and sends e-mail messages if alarms occur.
- Settings: Screen showing setup menus.
- Measurements: Relevant values can be chosen between all measured gen-set values.

For more information, please contact Atlas Copco.

## 14 Menu overview & changing parameters

## 14.1 Main View

The display has 4 different lines. The information on these lines can change, depending on which view is used. There are 4 different main views possible: SETUP / S1 / S2 / S3.

QC4001		V. 1.02.1	
2003-11-21		16:08:11	
SETUP MEN	U		
SETUP	S3	S2	S1

S3 VIEW			
	Phase	missing	
G	0,001	PF	0kW
G		0 kVA	0 kvar
SETUP	<u>S3</u>	S2	S1

## S2 VIEW

S2 VIEW				S1 VIEW			
G	(	0	0 0 A		Run Tim	ne	0Hour
G	0,001	PF	0kW	Fuel level			100%
G		0 kVA	0 kvar	2003-11-21		16:08:1	11
SETUP	S3	<u>S2</u>	S1	SETUP	S3	S2	<u>S1</u>

The user can scroll through these views with the scroll buttons.

## 14.2 SETUP menu

The SETUP view shows the module name, the software version, the date and the time. If you select SETUP then you get the following view :

G	0,001	PF	0kW
I-L1			0A
PROTEC	TION SET	UP	
PROT	CTRL	POWER	SYST

The fourth line is the entry selection for the Menu system. If the SELECT button is pressed, the selection of the menu indicated with an underscore will be entered. Choices are:

protection setup
controls setup
power control setup
system setup

The user can scroll to these choices with the scroll buttons.

## 14.2.1 If the PROTECTION SETUP is selected

The following view will appear (example of parameter) :

G		0,001	PF	(	0kW
	1210	Gen higl	n-volt 1		
	:	Set poin	t	1	05,00%
LIM	DEL	OA	OB	ACT	FC

For a protective function the first entry shows the "gen high volt 1" setting. Scrolling down will give all the protection parameters.

**The first line** shows some generator data. There are 7 different information lines possible. The user can scroll through with the VIEW button.

G	0,001	PF	0 kW		
G	0 k'	VA	0 kvar		
G-L1	0.0	0.0 Hz			
B-L1	0.0	0.0 Hz			
G	0	0	0 V		
В	0	0	0 V		
G	0	0	0 A		

**The second line** shows the channel number and the name of the parameter. The user can scroll through with the scroll buttons.

The third line shows the value of a setpoint of this parameter.

The fourth line shows the different possible setpoints. In this example:

"LIM"	= LIMIT, setting of switch point
"DEL"	= DELAY, setting of time delay
"OA"	OUTPUT A, selection of which relay the function must activate
"OB"	OUTPUT B, selection of which relay the function must activate
"ACT"	ACTION, activate/de-activate the function
"FC"	FAIL CLASS, fail class setting.

The user can scroll to these choices with the scroll button, and select one choice with the SELECT button. After selection of 'LIM' the following view will be visible:

G	0,001	PF	0kW
ENTER PASSWORD			1999
ENTER			

A password is needed in order to change the settings. There are 3 different password levels.

If the correct password is entered, the following view appears:

G	0,001	PF	0kW			
	1211 Gen high	n-volt 1				
	100,0,,,105,0,,,120,0%					
RESE	<u>:T</u>		SAVE			

Now the user can change the 'LIM' of parameter 'Gen high-volt 1'. This can be done with the scroll buttons.

Then the user has to select 'SAVE' to save the new settings.

To exit the user has to press the BACK button several time, till the main view appears.

This is the described menu flow:



## 14.2.2 If the CONTROL SETUP is selected

The following view will appear (example of parameter):

G	0,001	PF	0kW		
2020Synchronisation					
dfMax 0,3Hz					
fMax	<u>fMin</u>	Umax	TGB		

For control functions one entry shows the "Synchronisation" function. In this case the fourth line shows:

"fMax"	max allowed positive frequency deviation when synchronising
"fMin"	min allowed negative frequency deviation when synchronising
"Umax"	max allowed voltage deviation (positive/ negative) when
	synchronising.
"tCB"	closing time delay for generator circuit breaker.

Scrolling down gives all the other control parameters.

The setpoints can be changed as explained in the protection setup.

## 14.2.3 If POWER SETUP is selected

The following view will appear (example of parameter):

G	0,00I PF		0kW			
	3010Mains Pov	wer				
	Power 750 kW					
DAY	<u>NIGHT</u>	TRANS				

For power setup the first entry shows the "Mains power" setting. In this case the fourth line shows:

"DAY"	setting of max allowed imported power during the daytime
"NIGHT"	setting of max allowed imported power during the daytime
"TRANS"	setting of transducer scale for transducer used in peak shaving system.

Scrolling down gives all the other power parameters. The setpoints can be changed as explained in the protection setup.

## 14.2.4 If the SYSTEM SETUP is selected

The following view will appear (example of parameter) :

G	0,001	0kW			
	4010Nom. Settings				
	Frequency 50,0Hz				
F	Р	I	U		

For system setup the first entry shows the "Nominal settings". In this case the fourth line shows:

"P" nominal generator power setting

"I" nominal generator current setting

"U" nominal generator voltage setting

The above settings are used by the QC4001 to calculate the nominal apparent power and the power factor.

Scrolling down gives all the other system parameters.

The setpoints can be changed as explained in the protection setup.

# $\Rightarrow$

## 14.3 The JUMP button

Instead of navigating through the entire menu, the user can jump directly to the required parameter, if he knows the channel number of that specific parameter. For example, if the user wants to change 'language', he can jump directly to channel 4240.

If the JUMP button is pushed the password view will appear. Not all parameters can be changed by the end-user. The required password level for each parameter is given in the setpoint list.

## 14.4 S1 / S2 / S3 menu

The user can select 3 different views to read out information of gen-set, bus and mains.

S3 VIEW

	Dhace mi	aaina				
Phase missing						
G	0,001	PF	0kW			
G		0 kVA	0 kvar			
SETUP	<u><b>S3</b></u> S2 S1					

The S3 view shows operational status and selectable measurements During synchronisation the S3 view will show a synchronoscope in the first line. This is useful during manual synchronising.

## S2 VIEW

G		0	00A
G	0,001	PF	0kW
G		0 kVA	0 kvar
SETUP	S3	<u>S2</u>	S1

The S2 view shows selectable measurements.

S1 VIEW

	Run Time		0Hour
Fuel level		100	)%
2002-11-21		16:08:11	
SETUP	S3	S2	<u>S1</u>

In the S1 view the user can scroll up and down to 15 configurable screens showing different selectable measurements.

The configuration of the 15 different screens is done through the Qc4001 Utility Software. It is not possible to configure the windows through the display.

The screen shown when leaving "S1" will be the screen shown when returning to "S1".

If the text "No text" is selected in all three lines in a window it will not be displayed. This is to get a continuous displaying if a window is no longer to be shown.

The selectable values and measurements are shown in the table below:

I-L1	0 A	
I-L2	0 A	
I-L3	0 A	
Run time	0 Hour	
GB Operations	0	
0 822 0999 97-02	-	
MB Operations	0	
Mains P	- 156 kW	
Analog 1	5.5 mA	
Analog 2	5.5 mA	
Oil P	91 nsi	6.3 bar
Cool Temp	77 F	25 °C
Fuel Level	100 %	20 0
Analog 3	0.0 mA	
Analog 4	0.0 mA	
Analog 5	0.0 mA	
Analog 6	0.0  mA	
Tacho	0.0 mA	
Serv 1	0 d	40 h
Serv 2	1800 d	49 h 49 h
Engine I	value	ηση N Δ
Engine I.	value	N.A.
		N.A.
	0.00 HZ	
I-L2	0.00 HZ	
I-L3		
P		
5 Difector		
Angle LTL2	0 deg	
Angle L2L3	0 deg	
	0 deg	
U-Bus L1	0 V	
U-Bus L2	0 V	
U-Bus L3	0 V	
U-Bus L1L2	0 V	
U-Bus L2L3	0 V	
U-Bus L3L1	0 V	
U-BUS MAX	UV	
	UV	
t Bus	0.00 Hz	
Ang BusL1L2	U deg	
Ang Bus-Gen	0 deg	

U-Supply	24.6 V
E	0 MWh 0 kWh
U-Gen L1N	0 V
U-Gen L2N	0 V
U-Gen L3N	0V
U-Gen L1L2	0 V
U-Gen L2L3	0 V
U-Gen L3L1	0 V
U-Gen Max	0 V
U-Gen Min	0 V

## 14.5 Alarm and event list menu

When selecting the alarm (and event) list, the second line will display the latest alarm/event. The user can scroll through the list with the scroll buttons.

## 15 Password levels

There are 4 different levels:

- No password level
- Customer password level
- Service password level
- Master password level

The user can scroll through the entire menu without any password.

From the moment that the user wants to change a setpoint, a password will be required. Changing different parameters requires different password levels. Some parameters cannot be changed by the end-customer because of safety reasons.

Once the password has be entered, the user can change all the accessible setpoints. Only if no actions have been taken within 3 minutes, the password entry will be deactivated, and a new password entry will be needed.

The user can change the Customer password in channel 4971. *Beware:* Write down the new password. If you forget it, entering the menus will not be possible.

Service password and Master password can only be set through the Qc4001 Utility Software.

## 16 Fail classes

All the activated alarms of the Qc4001 must be configured with a fail class. The fail classes define the category of the alarms and the subsequent action of the alarm.

4 different fail classes can be used:

	Action					
Fail Class	Alarm Horn Relay	Alarm Display	GB Trip	Gen-Set Stop	Shutdown	
1.Warning	Х	Х				
2.Trip of GB	Х	Х	Х			
3.Trip & Stop	Х	Х	Х	Х		
4. Shutdown	Х	Х	Х		Х	

All alarms can be disabled or enabled as following:

- OFF disabled alarm, inactive supervision.
- ON enabled alarm, supervision of alarm all the time.
- RUN gen-set running alarm, only supervision when the gen-set is running.

## 17 Menu set-points

Each parameter has its specific channel number.

Changing a parameter requires a password. The password level is indicated for each parameter.



The set points are listed below in numerical order of channel number.

The default values depend on the type of gen-set. Some values are different for QIX,QAS and for QAC gen-sets. In the parameter list below we have taken the default values for a QAC gen-set.

## 17.1 Protection setup

17.1.1 Bus voltage protection

1010	Bus High Volt. 1		CUSTOMER LEVEL	
	1011	Setpoint	103,0%	(100.0 120.0)
	1012	Delay	10.00s	(0.10 99.99)
	1013	Output Relay A	R0	(R0 R3)
	1014	Output Relay B	R0	(R0 R3)
	1015	Enable	OFF	(OFF / RUN / ON)
	1016	Fail Class	Warning	(Warning / Trip / Trip+Stop / Shutdown)

1020 Bus High Volt. 2 SERVICE LEVEL 1021 (100.0 ... 150.0) Setpoint 108,0% 5.00s 1022 Delay (0.10 ... 99.99) 1023 Output Relay A R0 (R0 ... R3) 1024 Output Relay B R0 (R0 ... R3) 1025 Enable OFF (OFF / RUN / ON) 1026 Fail Class Trip (Warning / Trip / Trip+Stop / Shutdown)

#### 1030 Bus Low Volt. 1

#### CUSTOMER LEVEL

(80.0 ... 100.0) (0.10 ... 99.99) (R0 ... R3) (R0 ... R3) (OFF / RUN / ON) (Warning / Trip / Trip+Stop / Shutdown)

1040	1040 Bus Low Volt. 2			E LEVEL
	1041	Setpoint	92,0%	(50.0
	1042	Delay	5.00s	(0.10
	1043	Output Relay A	R0	(R0
	1044	Output Relay B	R0	(R0
	1045	Enable	OFF	(OFI
	1046	Fail Class	Trip	(Wa

50.0 ... 100.0) 0.10 ... 99.99) R0 ... R3) R0 ... R3) OFF / RUN / ON) Warning / Trip / Trip+Stop / Shutdown)

#### 17.1.2 Bus frequency protection

1050	Bus High	n Freq. 1	CUSTOMER LEVEL	
	1051	Setpoint	103,0%	(100.0 120.0)
	1052	Delay	10.00s	(0.10 99.99)
	1053	Output Relay A	R0	(R0 R3)
	1054	Output Relay B	R0	(R0 R3)
	1055	Enable	OFF	(OFF / RUN / ON)
	1056	Fail Class	Warning	(Warning / Trip / Trip+Stop / Shutdown)

Bus High	Freq. 2	SERVICE LEVEL
1061	Setpoint	105,0%
1062	Delay	5.00s
1063	Output Relay A	R0
1064	Output Relay B	R0
1065	Enable	OFF
1066	Fail Class	Trip

(100.0 ... 120.0) (0.10 ... 99.99) (R0 ... R3) (R0 ... R3) (OFF / RUN / ON) (Warning / Trip / Trip+Stop / Shutdown)

1070 Bus Lo	w Freq. 1	CUSTOMER LEVEL	
1071	Setpoint	97,0%	(8
1072	2 Delay	10.00s	((
1073	Output Relay A	R0	(/
1074	Output Relay B	R0	(/
1075	Enable	OFF	((
1076	Fail Class	Warning	()

80.0 ... 100.0) 0.10 ... 99.99) R0 ... R3) R0 ... R3) OFF / RUN / ON) Warning / Trip / Trip+Stop / Shutdown)

 1080
 Bus Low Freq. 2

 1081
 Setpoint

1060

## SERVICE LEVEL

1081	Setpoint	95,0%
1082	Delay	5.00s
1083	Output Relay A	R0
1084	Output Relay B	R0
1085	Enable	OFF
1086	Fail Class	Trip

(80.0 ... 100.0) (0.10 ... 99.99) (R0 ... R3) (R0 ... R3) (OFF / RUN / ON) (Warning / Trip / Trip+Stop / Shutdown)

## 17.1.3 Generator Reverse Power

Reverse power settings relates to nominal power setting.

1090	Reverse Power	SERVICE LEVEL	
	1091 Setpoint	-20,0%	(-50
	1092 Delay	5.00s	(0.1
	1093 Output Relay A	R0	(R0
	1094 Output Relay B	R0	(R0
	1095 Enable	ON	(OF
	1096 Fail Class	Trip + Stop	(Wá

50.0 ... 0.0) 0.1 ... 100.0) R0 ... R3) R0 ... R3) DFF / RUN / ON) Varning / Trip / Trip+Stop / Shutdown)

## 17.1.4 Generator Overcurrent Protection

Settings relates to nominal generator current setting.

1100	Over Current 1		CUSTOMER LEVEL	
	1101	Setpoint	110,0%	(50.0 200.0)
	1102	Delay	10.00s	(0.1 100.0)
	1103	Output Relay A	R0	(R0 R3)
	1104	Output Relay B	R0	(R0 R3)
	1105	Enable	ON	(OFF / RUN / ON)
	1106	Fail Class	Warning	(Warning / Trip / Trip+Stop / Shutdown)

1110	Over Cur	rent 2	SERVICE LEVEL
	1111	Setpoint	120,0%
	1112	Delay	5.00s
	1113	Output Relay A	R0
	1114	Output Relay B	R0
	1115	Enable	ON
	1116	Fail Class	Trip + Stop

(50.0 ... 200.0) (0.1 ... 100.0) (R0 ... R3) (R0 ... R3) (OFF / RUN / ON) (Warning / Trip / Trip+Stop / Shutdown)

## 17.1.5 Generator Overload Protection

Settings relates to nominal generator power setting.

1120	Over Load 1		CUSTOMER LEVEL	
	1121	Setpoint	110,0%	(1.0 200.0)
	1122	Delay	10.00s	(0.1 100.0)
	1123	Output Relay A	R0	(R0 R3)
	1124	Output Relay B	R0	(R0 R3)
	1125	Enable	ON	(OFF / RUN / ON)
	1126	Fail Class	Warning	(Warning / Trip / Trip+Stop / Shutdown)

1130	Over Loa	d 2	SERVICE LEVEL	
	1131	Setpoint	120,0%	(1.0 200.0)
	1132	Delay	5.00s	(0.1 100.0)
	1133	Output Relay A	R0	(R0 R3)
	1134	Output Relay B	R0	(R0 R3)
	1135	Enable	ON	(OFF / RUN / ON)
	1136	Fail Class	Trip + Stop	(Warning / Trip / Trip+Stop / Shutdown)
	-			

## 17.1.6 Generator Current Unbalance Protection

Settings relates to nominal generator current.

1140	Current Unbalance	SERVICE LEVEL	
	1141 Setpoint	30,0%	(0.0 1
	1142 Delay	10.00s	(0.1 1
	1143 Output Relay A	R0	(R0 R
	1144 Output Relay B	R0	(R0 R
	1145 Enable	OFF	(OFF / R
	1146 Fail Class	Trip + Stop	(Warning

0.0 ... 100.0) 0.1 ... 100.0) R0 ... R3) R0 ... R3) DFF / RUN / ON) Varning / Trip / Trip+Stop / Shutdown)

## 17.1.7 Generator Voltage Unbalance Protection

Settings relates to nominal generator voltage.

1150	Voltage Unbalar	nce	SERVICE LEVEL	
	1151 Setpoint		10,0%	(0.0 50.0)
	1152 Delay		10.00s	(0.1 100.0)
	1153 Output F	Relay A	R0	(R0 R3)
	1154 Output R	Relay B	R0	(R0 R3)
	1155 Enable		OFF	(OFF / RUN / ON)
	1156 Fail Clas	S	Trip + Stop	(Warning / Trip / Trip+Stop / Shutdown)

## 17.1.8 Generator Reactive Power Import (loss of excitation) Protection

1160	var Import	SERVICE LEVEL	
	1161 Setpoint	50,0%	(0.0 150.0)
	1162 Delay	10.00s	(0.1 100.0)
	1163 Output Relay	/ A <b>R0</b>	(R0 R3)
	1164 Output Relay	/ B <b>R0</b>	(R0 R3)
	1165 Enable	ON	(OFF / RUN / ON)
	1166 Fail Class	Warning	(Warning / Trip / Trip+Stop / Shutdown)

Settings relates to nominal generator power value (kW).

## 17.1.9 Generator Reactive Power Export (overexcitation) Protection

Settings relates to nominal generator power value (kW).

1170	var Export	SERVICE LEVEL	
	1171 Setpoint	50,0%	(0.0 100.0)
	1172 Delay	10.00s	(0.1 100.0)
	1173 Output Relay A	R0	(R0 R3)
	1174 Output Relay B	R0	(R0 R3)
	1175 Enable	ON	(OFF / RUN / ON)
	1176 Fail Class	Warning	(Warning / Trip / Trip+Stop / Shutdown)

## 17.1.10 Loss of Mains Protection

The loss of mains protection includes df/dt (Rate Of Change Of Frequency) protection. The protection is used when the generator is paralleling with the mains. When the protections are activated there is a fixed time delay of 1 second after the mains breaker closes. The loss of mains function trips the generator breaker.

NOTE: Time delay is in periods (per).

1180	Df/Dt (ROCOF)	SERVICE LEVEL	
	1181 Setpoint	5.0Hz/s	(0.1 10.0)
	1182 Delay	6 periods	(1 20)
	1183 Output Relay A	R0	(R0 R3)
	1184 Output Relay B	R0	(R0 R3)
	1185 Enable	OFF	(OFF / RUN / ON)

17.1.11 Vector jump

1190	Vector Jump	SERVICE LEVEL	_
	1191 Setpoint	10.0 deg	(1.0 90.0)
	1192 Output Relay A	R0	(R0 R3)
	1193 Output Relay B	R0	(R0 R3)
	1194 Enable	OFF	(OFF / RUN / ON)

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## 17.1.12 Generator voltage protection

1210

Gen High	n Volt. 1	CUSTOMER L	EVEL
1211	Setpoint	110,0%	
1212	Delay	5.0s	
1213	Output Relay A	R0	
1214	Output Relay B	R0	
1215	Enable	ON	
1216	Fail Class	Warning	

(100.0 ... 120.0) (0.1 ... 100.0) (R0 ... R3) (R0 ... R3) (OFF / RUN / ON) (Warning / Trip / Trip+Stop / Shutdown)

1220	Gen High	Volt. 2	MASTER LEVEL
	1221	Setpoint	120,0%
	1222	Delay	1.0s
	1223	Output Relay A	R0
	1224	Output Relay B	R0
	1225	Enable	ON
	1226	Fail Class	Shutdown

(100.0 ... 150.0) (0.1 ... 100.0) (R0 ... R3) (R0 ... R3) (OFF / RUN / ON) (Warning / Trip / Trip+Stop / Shutdown)

1230	Gen Low	Volt. 1	CUSTOMER L	EVEL
	1231	Setpoint	90,0%	(8
	1232	Delay	15.0s	(0
	1233	Output Relay A	R0	(F
	1234	Output Relay B	R0	(F
	1235	Enable	RUN	(0
	1236	Fail Class	Warning	(1/

(80.0 ... 100.0) (0.1 ... 100.0) (R0 ... R3) (R0 ... R3) (OFF / RUN / ON) (Warning / Trip / Trip+Stop / Shutdown)

1240	Gen Low	Volt. 2	SERVICE LEVEL	_
	1241	Setpoint	70,0%	
	1242	Delay	10.0s	
	1243	Output Relay A	R0	
	1244	Output Relay B	R0	
	1245	Enable	RUN	
	1246	Fail Class	Shutdown	

(50.0 ... 100.0) (0.1 ... 100.0) (R0 ... R3) (R0 ... R3) (OFF / RUN / ON) (Warning / Trip / Trip+Stop / Shutdown)

## 17.1.13 Generator frequency protection

1250	Gen High	req. 1	CUSTOMER LEV	EL
	1251	Setpoint	110,0%	(
	1252	Delay	5.0s	(
	1253	Output Relay A	R0	(
	1254	Output Relay B	R0	(
	1255	Enable	ON	(
	1256	Fail Class	Warning	(

(100.0 ... 120.0) (0.2 ... 100.0) (R0 ... R3) (R0 ... R3) (OFF / RUN / ON) (Warning / Trip / Trip+Stop / Shutdown)

1260	Gen High	n Freq. 2	MASTER LEVEL	
	1261	Setpoint	120,0%	(
	1262	Delay	1.0s	(
	1263	Output Relay A	R0	(
	1264	Output Relay B	R0	(
	1265	Enable	ON	(

(100.0 ... 120.0) (0.2 ... 100.0) (R0 ... R3) (R0 ... R3) (OFF / RUN / ON)

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```
1266
     Fail Class
                          Shutdown
```

(Warning / Trip / Trip+Stop / Shutdown)

1270

Gen Low Freq. 1		CUSTOMER LI	EVEL
1271	Setpoint	90,0%	
1272	Delay	10.0s	
1273	Output Relay A	R0	
1274	Output Relay B	R0	
1275	Enable	RUN	
1276	Fail Class	Warning	

(80.0 ... 100.0) (0.2 ... 100.0) (R0 ... R3) (R0 ... R3) (OFF / RUN / ON) (Warning / Trip / Trip+Stop / Shutdown)

1280	Gen Low	Freq. 2	SERVICE LEVEL	
	1281	Setpoint	80,0%	(80.0 100.0)
	1282	Delay	5.0s	(0.2 100.0)
	1283	Output Relay A	R0	(R0 R3)
	1284	Output Relay B	R0	(R0 R3)
	1285	Enable	RUN	(OFF / RUN / ON)
	1286	Fail Class	Shutdown	(Warning / Trip / Trip+Stop / Shutdown)

## 17.1.14 Engine control

The configuration of the engine interface card is done in the next channel groups. Configuration of the inputs is done through the display and the Qc4001 Utility Software.

## 17.1.15 Mains Power 4...20 mA input

The input is not configurable because it is used as a mains power input in the peak shaving mode.

## 17.1.16 Configurable 4...20 mA input 1

1310	10 420mA Input 1.1		CUSTOMER L	CUSTOMER LEVEL		
	1311	Setpoint	10.0mA	(0.0 20.0)		
	1312	Delay	15.0s	(0.0 600.0)		
	1313	Output Relay A	R0	(R0 R3)		
	1314	Output Relay B	R0	(R0 R3)		
	1315	Enable	OFF	(OFF / RUN / ON)		
	1316	Fail Class	Warning	(Warning / Trip / Trip+Stop / Shutdown)		
	USW	Alarm type	High	(Low / High)		

1320 4...20mA Input 1.2

#### **CUSTOMER LEVEL** 1321 Setpoint 10.0mA (0.0 ... 20.0) (0.0 ... 600.0) 1322 Delay 15.0s 1323 Output Relay A R0 (R0 ... R3) 1324 Output Relay B (R0 ... R3) R0 (OFF / RUN / ON) OFF 1325 Enable (Warning / Trip / Trip+Stop / Shutdown) 1326 Fail Class Warning USW Alarm type High (Low / High)

High alarm = alarm when the actual value is higher than the setpoint.

## 17.1.17 Configurable 4...20 mA input 2

1330	420mA	Input 2.1	CUSTOMER LEVEL	
	1331	Setpoint	10.0mA	(0.0 20.0)
	1332	Delay	15.0s	(0.0 600.0)
	1333	Output Relay A	R0	(R0 R3)
	1334	Output Relay B	R0	(R0 R3)
	1335	Enable	OFF	(OFF / RUN / ON)
	1336	Fail Class	Warning	(Warning / Trip / Trip+Stop / Shutdown)
	USW	Alarm type	High	(Low / High)
	USW	Alarm type	High	(Low / High)

## 1340 <u>4...20mA Input 2.2</u> CUSTOMER LEVEL

1341	Setpoint	10.0mA	(0.0 20.0)
1342	Delay	15.0s	(0.0 600.0)
1343	Output Relay A	R0	(R0 R3)
1344	Output Relay B	R0	(R0 R3)
1345	Enable	OFF	(OFF / RUN / ON)
1346	Fail Class	Warning	(Warning / Trip / Trip+Stop / Shutdown)
USW	Alarm type	High	(Low / High)

High alarm = alarm when the actual value is higher than the setpoint

## 17.1.18 Configurable VDO input 1

This input will be used for a resistive Engine Oil Pressure VDO sensor or for a 'fail-safe' VDO Coolant Level Switch.

A sensor type must be software selectable (2 pressure sensors, 1 level switch & 1 configurable curve (8 points to be defined)).

If a pressure sensor is selected, the displayed value will be in bar and psi. If the level switch is selected, there's no value to be displayed.

1350	VDO 1.1		SERVICE LEVEL	
	1351	Setpoint	N/A	(0.0 10.0)
	1352	Delay	5.0s	(0.0 100.0)
	1353	Output Relay A	R0	(R0 R3)
	1354	Output Relay B	R0	(R0 R3)
	1355	Enable	OFF	(OFF / RUN / ON)
	1356	Fail Class	Warning	(Warning / Trip / Trip+Stop / Shutdown)
	USW	Sensor Type	N/A	(0 / 1 / 2 / 3)

1360	VDO 1.2		MASTER LEVEL	
	1361	Setpoint	N/A	(0.0 10.0)
	1362	Delay	5.0s	(0.0 100.0)
	1363	Output Relay A	R0	(R0 R3)
	1364	Output Relay B	R0	(R0 R3)
	1365	Enable	OFF	(OFF / RUN / ON)
	1366	Fail Class	Warning	(Warning / Trip / Trip+Stop / Shutdown)

The 'Sensor Type' and 'Alarm Type' parameters will only be accessible through the Atlas Copco Qc4001 Utility Software, and not through the display menu.

Pressure	Sender 0	Sender 1
	(ohm)	(ohm)
0 bar	10.0	10.0
0.5 bar	27.2	
1 bar	44.9	31.3
1.5 bar	62.9	
2 bar	81.0	51.5
2.5 bar	99.2	
3 bar	117.1	71.0
3.5 bar	134.7	
4 bar	151.9	89.6
4.5 bar	168.3	
5 bar	184.0	107.3
6 bar		124.3
7 bar		140.4
8 bar		155.7
9 bar		170.2
10 bar		184.0

Sender 2 : Coolant Level Switch: Normal situation: resistive value > 200 ohm ; Alarm situation: resistive value < 200 ohm.

Sender 3 : configurable 0 – 10 bar (parameter 5010 - 5020).

## 17.1.19 Configurable VDO input 2

This input will be used for a resistive Engine Coolant Temperature VDO sensor or for an Alternator Temperature PTC.

A sensor type must be software selectable (3 temperature sensors, 1 PTC & 1 configurable curve (8 points to be defined)).

If a temperature sensor is selected, the displayed value will be in °C and °F. If the PTC is selected, there's no value to be displayed.

1370	High alte	rnator Temperature	SERVICE LEVEL	
	1371	Setpoint	N/A	(40 150)
	1372	Delay	3.0s	(0.0 100.0)
	1373	Output Relay A	R0	(R0 R3)
	1374	Output Relay B	R0	(R0 R3)
	1375	Enable	OFF	(OFF / RUN / ON)
	1376	Fail Class	Warning	(Warning / Trip / Trip+Stop / Shutdown)
	USW	Sensor Type	3	(0 / 1 / 2 / 3 / 4)

1380	VDO 2.2		SERVICE LEVEL	
	1381	Setpoint	N/A	(40 150)
	1382	Delay	5.0s	(0.0 100.0)
	1383	Output Relay A	R0	(R0 R3)
	1384	Output Relay B	R0	(R0 R3)
	1385	Enable	OFF	(OFF / RUN / ON)
	1386	Fail Class	Warning	(Warning / Trip / Trip+Stop / Shutdown)

The 'Sensor Type' and 'Alarm Type' parameters will only be accessible through the Atlas Copco Qc4001 Utility Software, and not through the display menu.

Temperature	Sender 0	Sender 1	Sender 2
	(ohm)	(ohm)	(ohm)
40 °C	291.5	480.7	69.3
50 °C	197.3	323.6	
60 °C	134.0	222.5	36.0
70 °C	97.1	157.1	
80 °C	70.1	113.2	19.8
90 °C	51.2	83.2	
100 °C	38.5	62.4	11.7
110 °C	29.1	47.6	
120 °C	22.4	36.8	7.4
130 °C		28.9	
140 °C		22.8	
150 °C		18.2	

Sender 3 : Alternator Temperature PTC: Normal Situation: resistive value < 1k7 ; Alarm situation: resistive value > 1k7.

## Sender 4 : Configurable 40 – 110 °C (parameter 5030 – 5040).
# 17.1.20 Configurable VDO input 3

This input will be used for a resistive Fuel Level VDO sensor.

A sensor type must be software selectable (2 level sensors & configurable curve (8 points to be defined)).

The displayed value will be in %.

1390	Fuel Le	vel 1	CUSTOMER LEVEL	
	1391	Setpoint 1	10,0%	(0 100)
	1392	Delay	10.0s	(0.0 100.0)
	1393	Output Relay A	R0	(R0 R3)
	1394	Output Relay B	R0	(R0 R3)
	1395	Enable	ON	(OFF / RUN / ON)
				(Warning / Trip / Trip+Stop /
	1396	Fail Class	Warning	Shutdown)
	USW	Sensor Type	1	(0 / 1 / 2)

Resistive Fuel Level Sender 0: Linear: 0 % = 78.8 ohm ; 100 % = 1.6 ohm. Resistive Fuel Level Sender 1: Linear: 0 % = 3 ohm ; 100 % = 180 ohm. Resistive Fuel Level Sender 2: Configurable 0 - 100 % (parameter 5050 - 5060).

The fuel pump logics will also use this input to start/stop the fuel pump when necessary.

# 1400 Fuel Pump Logic

ruei Pump Logic	CUSTOWER LEVEL	
1401 Setpoint 2	20,0%	(0 100)
1402 Setpoint 3	80.0%	(0 100)
1403 Relay Output Pump	R4	(R0 R3)
1404 Enable Pump Logics	OFF	(OFF / RUN / ON)
1405 Fill Check Delay	60.0s	(0.1 600.0)

# Fuel Pump Logics:

If the fuel level is below 'set-point 2', the 'relay output pump' will be energised. This 'relay output pump' will stay energised until the fuel level reaches 'set-point 3', until a general failclass 3 or 4 occurs, until the controller is powered off.

When the 'relay output pump' is energised, and the fuel level hasn't risen during the fill chack delay, the 'relay output pump' will be de-energised and a failclass 1 alarm 'Fuel Fill Pump Error' will be displayed.

Set-point 4 will be an extra high alarm. This set-point can operate a relay output defined in 1467.

1410	Fuel High level	CUSTOMER LEVEL	
	1411 Setpoint 4	98,0%	(0 100)
	1412 Delay	5.0s	(0.1 300.0)
	1413 Output Relay A	R0	(R0 R3)
	1414 Output Relay B	R0	(R0 R3)

Set-point 4 will be an extra high alarm.

### 17.1.21 Overspeed (tacho input)

1420	Overspee	ed	MASTER LEVEL	
	1421	Setpoint	1650rpm	(1 2250)
	1422	Delay	3.0s	(0.2 100.0)
	1423	Output Relay A	R1	(R0 R3)
	1424	Output Relay B	R0	(R0 R3)
	1425	Enable	ON	(OFF / RUN / ON)
	1426	Fail Class	Shutdown	(Warning / Trip / Trip+Stop / Shutdown)
				· · · · · · · · ·

1430	Overspee	ed	MASTER LEVEL	_
	1431	Overspeed S2	1980rpm	(1 2250)
	1432	Overspeed S3	1650rpm	(1 2250)
	1433	Overspeed S4	1650rpm	(1 2250)

Overspeed S2 set-point is used when the 2<sup>nd</sup> set of parameters are active. Overspeed S3 set-point is used when the 3<sup>rd</sup> set of parameters are active. Overspeed S4 set-point is used when the 4<sup>th</sup> set of parameters are active.

17.1.22 Ext. Engine Failure (binary input 8)

1440	Engine	Failure	SERVICE LEVEL	
	1441	Delay	1.0s	(0.0 180.0)
	1442	Output Relay A	R0	(R0 R3)
	1443	Output Relay B	R0	(R0 R3)
	1444	Enable	ON	(OFF / RUN / ON)
	1445	Fail Class	Shutdown	(Warning / Trip / Trip+Stop / Shutdown)

### 17.1.23 Emergency Stop (binary input 9)

1450	Emergency Stop	MASTER LEVEL	
	1451 Delay	0.0s	(0.0 60.0)
	1452 Output Relay A	R0	(R0 R3)
	1453 Output Relay B	R0	(R0 R3)
	1454 Enable	ON	(OFF / RUN / ON)
	1455 Fail Class	Shutdown	(Warning / Trip / Trip+Stop / Shutdown)

### 17.1.24 Non-configurable Sprinkler Input

Input 10 (terminal 118) can be configured as 'Sprinkler'. When 'Sprinkler' is selected, all alarms and fail classes are overruled. The only alarms the gen-set will react on are 'Emergency Stop' on terminal 117 or a 'Tacho Failure'. Also the gen-set has 7 start attempts before 'Start Failure'.

### 17.1.25 Coolant Temperature 1

A set-point can be configured for the coolant temperature value, that is read from the engine electronics over the CanBus.

1460	Coolant Temperature 1	SERVICE LEVEL	
	1461 Setpoint	100 deg	(0 150.0)
	1462 Delay	3.0s	(0.0 600.0)
	1463 Output Relay A	R0	(R0 R3)
	1464 Output Relay B	R0	(R0 R3)
	1465 Enable	ON	(OFF / RUN / ON)
	1466 Fail Class	Warning	(Warning / Trip / Trip+Stop / Shutdown)
	USW Alarm type	High	(Low / High)

High alarm = alarm when the actual value is higher than the setpoint.

### 17.1.26 Coolant Temperature 2

A set-point can be configured for the coolant temperature value, that is read from the engine electronics over the CanBus.

1470	Coolant Temperature 2	SERVICE LEVEL	
	1471 Setpoint	108 deg	(0 150.0)
	1472 Delay	3.0s	(0.0 600.0)
	1473 Output Relay A	R0	(R0 R3)
	1474 Output Relay B	R0	(R0 R3)
	1475 Enable	ON	(OFF / RUN / ON)
	1476 Fail Class	Shutdown	(Warning / Trip / Trip+Stop / Shutdown)
	USW Alarm type	High	(Low / High)
	1476 Fail Class USW Alarm type	Shutdown High	(Warning / Trip / Trip+Stop / Shutdown) (Low / High)

High alarm = alarm when the actual value is higher than the setpoint.

### 17.1.27 Oil Pressure

Here, a set-point can be configured for the oil pressure value, that is read from the engine electronics over the CanBus.

1480	Oil Pressure	SERVICE LEVEL	
	1481 Setpoint	3.0 bar	(0.0 15.0)
	1482 Delay	15.0s	(0.0 600.0)
	1483 Output Relay A	R0	(R0 R3)
	1484 Output Relay B	R0	(R0 R3)
	1485 Enable	RUN	(OFF / RUN / ON)
	1486 Fail Class	Warning	(Warning / Trip / Trip+Stop / Shutdown)
	USW Alarm type	Low	(Low / High)
	1484Output Relay B1485Enable1486Fail ClassUSWAlarm type	R0 RUN Warning Low	(R0 R3) (OFF / RUN / ON) (Warning / Trip / Trip+Stop / Shutdowr (Low / High)

Low alarm = alarm when the actual value is lower than the setpoint.

## 17.1.28 Fuel Level 2

This input will be used for a resistive Fuel Level VDO sensor. The displayed value will be in %.

1490	Fuel Le	evel 2	CUSTOMER LEVEL	
	1391	Setpoint 1	5,0%	(0 100)
	1392	Delay	20.0s	(0.0 100.0)
	1393	Output Relay A	R0	(R0 R3)
	1394	Output Relay B	R0	(R0 R3)
	1395	Enable	ON	(OFF / RUN / ON)
				(Warning / Trip / Trip+Stop /
	1396	Fail Class	Trip + Stop	Shutdown)

17.1.29 Configurable binary input 11 – 17 (optional)

These settings will only be visible when the Qc4001 module contains the optional extension card with 7 binary inputs.

The reserved channels for these parameters are 1600 - 1666.

17.1.30 2nd Set of Parameters (binary input 18)

This input will be dedicated for a 2<sup>nd</sup> set of parameters input (see channel 4020: nominal settings 2).

When this input is made active, some of the settings will be re-set to another level. No configuration of this input must be possible.

17.1.31 3rd Set of Parameters (binary input 19)

This input will be dedicated for a 3<sup>rd</sup> set of parameters input (see channel 4030: nominal settings 3).

When this input is made active, some of the settings will be re-set to another level. No configuration of this input must be possible.

17.1.32 4th Set of Parameters (binary input 20)

This input will be dedicated for a 4th set of parameters input (see channel 4040: nominal settings 4).

When this input is made active, some of the settings will be re-set to another level. No configuration of this input must be possible.

### 17.1.33 Configurable binary input 21

1700	Digital Input 21	COSTUMER LEVEL	
	1701 Delay	10.0s	(0.0 100.0)
	1702 Output Relay A	R0	(R0 R3)
	1703 Output Relay B	R0	(R0 R3)
	1704 Enable	OFF	(OFF / RUN / ON)
			(Warning / Trip / Trip+Stop /
	1705 Fail Class	Warning	Shutdown)
	1706 Type	High	(Low / High)
1.12.1		( )	

High alarm = Alarm when the input closes

### 17.1.34 Configurable binary input 22

For the QAC gensets this input is dedicated to 'Manual Fuel fill'.

1710	Man. Fuel Fill	SERVICE LEVEL	
	1711 Delay	0.0s	(0.0 100.0)
	1712 Output Relay A	R4	(R0 R3)
	1713 Output Relay B	R0	(R0 R3)
	1714 Enable	ON	(OFF / RUN / ON)
			(Warning / Trip / Trip+Stop /
	1715 Fail Class	Warning	Shutdown)
	1716 Type	High	(Low / High)
			—

High alarm = Alarm when the input closes

# 17.1.35 Configurable binary input 23

For the QAC gen-sets this input is dedicated to 'Air Shut off'.

1720	Air Shut Off	SERVICE LEVEL
	1721 Delay	0.2s
	1722 Output Relay A	R0
	1723 Output Relay B	R0
	1724 Enable	ON
	1725 Fail Class	Shutdown
	1726 Type	High

High alarm = Alarm when the input closes

(0.0 ... 100.0) (R0 ... R3) (R0 ... R3) (OFF / RUN / ON) (Warning / Trip / Trip+Stop / Shutdown) (Low / High)

# 17.1.36 Configurable binary input 24

For the QAC gen-sets this input is dedicated to 'Fan Failure'.

1730 Fan Fa

Fan Failure	SERVICE LEVEL
1731 Delay	60.0s
1732 Output Relay A	R0
1733 Output Relay B	R0
1734 Enable	RUN
1735 Fail Class	Trip + Stop
1736 Type	High
	-

(0.0 ... 100.0) (R0 ... R3) (R0 ... R3) (OFF / RUN / ON) (Warning / Trip / Trip+Stop / Shutdown) (Low / High)

High alarm = Alarm when the input closes

17.1.37 Configurable binary input 25

For the QAC gen-sets this input is dedicated to 'Low coolant Level'.

1740	Low Coolant Level	SERVICE LEVEL	
	1741 Delay	10.0s	(0.0 100.0)
	1742 Output Relay A	R0	(R0 R3)
	1743 Output Relay B	R0	(R0 R3)
	1744 Enable	ON	(OFF / RUN / ON)
	1745 Fail Class	Warning	(Warning / Trip / Trip+Stop / Shutdown)
	1746 Type	High	(Low / High)
1.12 - 1-	Alama Alama	1 . 1	—

High alarm = Alarm when the input closes

### 17.1.38 Configurable binary input 26

For the QAC gensets this input is dedicated to 'Tank leakage'.

1750 Tank leakage		SERVICE LEVEL	
	1751 Delay	10.0s	
	1752 Output Relay A	R0	
	1753 Output Relay B	R0	
	1754 Enable	ON	
	1755 Fail Class	Warning	
	1756 Type	High	

(0.0 ... 100.0) (R0 ... R3) (R0 ... R3) (OFF / RUN / ON) (Warning / Trip / Trip+Stop / Shutdown) (Low / High)

High alarm = Alarm when the input closes

# 17.1.39 Configurable binary input 27

For the QAC gen-sets this input is dedicated to 'DDEC check engine'.

1760 DDEC Check Engine SERVICE LEVEL

1761 Delay	1.0s
1762 Output Relay A	R0
1763 Output Relay B	R0
1764 Enable	RUN
1765 Fail Class	Warning
1766 Type	Low

(0.0 ... 100.0) (R0 ... R3) (R0 ... R3) (OFF / RUN / ON) (Warning / Trip / Trip+Stop / Shutdown) (Low / High)

Low alarm = Alarm when the input opens

### 17.1.40 Configurable binary input 28

For the QAC gen-sets this input is dedicated to 'Terminal Board open'.

1770	T.B. Open	SERVICE LEVEL	
	1771 Delay	0.0s	(0.0 100.0)
	1772 Output Relay A	R0	(R0 R3)
	1773 Output Relay B	R0	(R0 R3)
	1774 Enable	ON	(OFF / RUN / ON)
	1775 Fail Class	Trip	(Warning / Trip / Trip+Stop / Shutdown)
	1706 Type	High	(Low / High)

High alarm = Alarm when the input closes

### 17.1.41 Configurable binary input 29

This input can not only enable, but also disable a relay output. For the QAC gen-sets this input is dedicated to 'DDEC Stop Engine'

1780	DDEC Stop Engine	SERVICE LEVEL	
	1781 Delay	1.0s	
	1782 Enable Output Relay	R0	
	1783 Disable Output Relay	R0	
	1784 Enable	RUN	
	1785 Fail Class	Shutdown	
	1786 Type	High	
		1	

(0.0 ... 100.0) (R0 ... R3) (R0 ... R3) (OFF / RUN / ON) (Warning / Trip / Trip+Stop / Shutdown) (Low / High)

High alarm = Alarm when the input closes

# 17.1.42 Configurable (binary input 30)

This input can not only enable, but also disable a relay output.

1790 Digital Inc

Digital Input 30	CUSTOMER LEVEL
1791 Delay	10.0s
1792 Enable Output Relay	R0
1793 Disable Output Relay	R0
1794 Enable	OFF
1795 Fail Class	Warning
1796 Туре	High

(0.0 ... 100.0) (R0 ... R3) (R0 ... R3) (OFF / RUN / ON) (Warning / Trip / Trip+Stop / Shutdown) (Low / High)

High alarm = Alarm when the input closes

17.1.43 Configurable 4...20 mA input (optional)

These settings will only be visible when the Qc4001 module contains the optional extension card with 4 analogue inputs.

The reserved channels for these parameters are 1800 – 1856.

17.1.44 Run Status

All alarms can be:

- Disabled (OFF)
- Enabled all the time (ON)
- Enabled while the gen-set runs (RUN)

In case of 'enabled while gen-set runs' the alarms are monitored from when the generator is in running status.

1860	Run Status		SERVICE LEVEL		
	1861	Delay	5.0s		(0.0 60.0)
	1862	Output Relay A	R0		(R0 R3)
	1863	Output Relay B	R0		(R0 R3)
	1864	Enable	OFF		(OFF / ON)

17.1.45 Remote Start/Stop (binary input 31)

This input will be dedicated for a remote start/stop command.

Closing a remote hard-wired switch, connected to this input, will start the gen-set and control its functions according the selected mode.

Opening of this switch will stop the gen-set according the selected mode.

This Remote Start/Stop can be used in Island Mode, in Fixed Power Mode and in Load Take Over Mode. It is active when the QC4001 is in "AUTO" mode and when all Real Time Clock Start/Stop Commands are disabled.

17.1.46 W/L (binary input 32)

This input will be dedicated for the charging feedback signal (W/L signal) of the charging alternator.

1870 W/I Input

0	W/L Input		SERVICE LEV	EL
	1871	Delay	3.0s	(0.0 100.0)
	1872	Output Relay A	R0	(R0 R3)
	1873	Enable	RUN	(OFF / ON)
	1874	Туре	Low	(Low / High)

Low alarm = Alarm when the input opens

17.1.47 Disable Analogue Fuel Input (binary input 33)

This input will be dedicated for following purpose:

If the input is made high, the controller disables the analogue VDO fuel input. Then there will be no fuel level displayed, and all warnings, shutdowns or fuel pump actions will be disabled as well.

17.1.48 Static Charger (binary input 34)

This input will be dedicated for the static battery charger feedback signal. This will only be monitored if the bus/mains voltage is present.

1880	Static Charger		SERVICE LEVEL	
	1881	Delay	10.0s	(0.0 100.0)
	1882	Output Relay A	R0	(R0 R3)
	1883	Enable	ON	(OFF / ON)
	1884	Туре	High	(Low / High)
ما به ال		arm when the input closes		

High alarm = Alarm when the input closes

# 17.1.49 MDEC Run Signal

With a MDEC engine controller it is possible to connect an extra running signal from the engine controller to the Qc4001. This is default not connected and therefore disabled.

1890	MDEC	Run Signal	SERVICE LEVEL	-
	1891	Delay	10.0s	(0.0 100.0)
	1892	Output Relay A	R0	(R0 R3)
	1893	Output Relay B	R0	(R0 R3)
	1894	Enable	OFF	(OFF / ON)

### 17.2 Control setup

17.2.1 Synchronisation type

2010	Sync. Type	SERVICE LEVEL	
	2011 Sync. Type	Dynamic Sync.	(Dynamic Sync. / Static Sync.)

If dynamic synchronisation is chosen, the next menu will be 2020. If static synchronisation is chosen, the next menu will be 2030.

### 17.2.2 Dynamic synchronisation

The setting of df max. and df min. decides whether the generator synchronises when running faster or slower than nominal frequency.

The "dU max." setting is related to nominal generator voltage. The "dU max." setting is +/- nominal generator voltage.

The Qc4001 module compensates for the breaker delay time when synchronising.

2020	Dynam	ic Sync.	SERVICE LEVEI	<u></u>
	2021	Df max.	0.3Hz	(0.0 0.5)
	2022	Df min.	0.0Hz	(-0.5 0.3)
	2023	DU max.	5%	(2 10)
	2024	Breaker Delay	75ms	(40 300)

The synchronisation pulse is 400 ms.

### 17.2.3 Static synchronisation

The phase gain and frequency gain are the control parameters used during static synchronisation. They both control the governor output.

The phase controller will keep the angle between the generator voltage and the busbar voltage within the closing window. The frequency controller will keep the generator frequency and the busbar frequency at the same value.

2030	Static Sync.	SERVICE LEVEL	
	2031 GB Close Time	1.0s	(0.0 100.0)
	2032 Closing Window	10.0 deg	(0.1 20.0)
	2033 Phase Gain	40	(0 100)
	2034 Frequency Gain	40	(0 100)

The synchronisation pulse is 400 ms.

### 17.2.4 Blackout closing of breaker

Settings are accepted limits (generator voltage and frequency) for closing the generator breaker. The "dU max." setting is related to nominal generator voltage.

2050	0 Sync. Blackout		SERVICE LEVEL	
	2051	Df max.	3.0Hz	(0.0 5.0)
	2052	DU max.	8%	(2 10)

If blackout closing of breaker is enabled on more units, external precautions must be taken to avoid two or more generators closing on a black busbar. In that case synchronism will not be present.

17.2.5 Generator and mains breaker, general failure alarm

- Synchronisation time

- Phase sequence error

- Breaker ON/OFF feedback fail

Adjustable time delay channel 2061/2071 1 second fixed time delay 1 second fixed time delay

2060	GB Sync	hr. Fail	SERVICE LEVEL	
	2061	Delay	60.0s	(30.0 300.0)
	2062	Output Relay A	R0	(R0 R3)
	2063	Output Relay B	R0	(R0 R3)
				_

2070	MB Sync	hr. Fail	SERVICE LEVEL	_
	2071	Delay	60.0s	(30.0 300.0)
	2072	Output Relay A	R0	(R0 R3)
	2073	Output Relay B	R0	(R0 R3)

The general failure alarms cannot be disabled.

### 17.2.6 Frequency Controller

The Frequency KP and KI parameter are used for the speed settings on the genset. The proportional controller (Kp) will have the effect of reducing the rise time and will reduce ,but never eliminate the steady-state error. The integral control (Ki) will have the effect of eliminating the steady-state error. To have a quick and stable frequency both parameters needs to be adjusted and fine-tuned.

Frequency deadband % settings relate to nominal generator frequency.

2090	Freq. Control	CUSTOMER LEVEL	
	2091 Deadband	0.2%	(0.2 10.0)
	2092 Frequency KP	35	(0 1000)
	2093 Frequency KI	150	(0 1000)

## 17.2.7 Power Controller

The Power KP and KI parameter are used for the power settings on the genset. The proportional controller (Kp) will have the effect of reducing the rise time and will reduce ,but never eliminate the steady-state error. The integral control (Ki) will have the effect of eliminating the steady-state error. To have a quick and stable power output both parameters needs to be adjusted and fine-tuned.

Power deadband % settings relate to nominal generator power.

2100	Power Co	ontrol	CUSTOMER LEVE	L
	2101	Deadband	0.2%	(0.2 10.0)
	2102	Power KP	15	(0 1000)
	2103	Power KI	100	(0 1000)

17.2.8 Power ramp up / Power ramp down

The delay point and time is the point where the generator stops ramping after closing of generator breaker to pre-heat the engine before commencing to take load. The time duration of the point is determined by the delay time setting. If the delay function is not needed, set the time to 0.

Power % settings relate to nominal generator power.

2110	Power R	amp Up	CUSTOMER LEVEL	
	2111	Speed	10%/s	(1.0 20.0)
	2112	Delay Point	10%	(1 100)
	2113	Delay Time	0.0s	(0.0 180.0)

### 17.2.9 Power ramp down

The breaker open point is where a relay output is activated to open the generator breaker before reaching 0 kW.

Power % settings relate to nominal generator power.

2120	Power Ramp Down	CUSTOMER LEVEL	
	2121 Speed	10%/s	(0.1 20.0)
	2122 Breaker Open	5%	(1 20)

### 17.2.10 Voltage controller

The Voltage KP and KI parameter are used for the voltage settings on the genset. The proportional controller (Kp) will have the effect of reducing the rise time and will reduce ,but never eliminate the steady-state error. The integral control (Ki) will have the effect of eliminating the steady-state error. To have a quick and stable voltage parameters needs to be adjusted and fine-tuned.

The voltage controller is active when the generator is in island mode. Voltage deadband % settings relate to nominal generator voltage.

2140	Voltage (	Control	CUSTOMER LEVE	L
	2141	Deadband	0.2%	(0.02 10.0)
	2142	KP	200	(0 1000)
	2143	KI	450	(0 1000)

### 17.2.11 Var controller

The Var KP and KI parameter are used for the reactive power settings on the genset. The proportional controller (Kp) will have the effect of reducing the rise time and will reduce, but never eliminate., the steady-state error. The integral control (Ki) will have the effect of eliminating the steady-state error. To have a quick and stable reactive power both parameters needs to be adjusted and finetuned.

Frequency deadband % settings relate to nominal generator frequency. Var deadband % settings relate to nominal generator power value, i.e. it is assumed that the generator var value is the same as the kW value. This is not correct, but the assumption is made for control purposes only.

The var controller is active when the generator is parallel to mains controlling the PF.

CUSTOMED I EVEL

2150	var	Control

50				
	2151	Deadband	0.2%	(0.0 10.0)
	2152	KP	30	(0 1000)
	2153	KI	150	(0 1000)

### 17.2.12 PF Control

The Power Factor deadband is put in percentage of the nominal PF setpoint for fixed power applications (parameter 3080). For fixed power application it can be necessary to change this deadband.

2170	PF Control		COSTUMER LEVEL	
	2171	Deadband	5%	(0 10)

### 17.2.13 Governor regulation failure

The alarm is activated if the difference between the measured value and the set-point is outside the deadband for longer than the timer set-point.

2180	Gov. Reg. Failure	SERVICE LEVEL	
	2181 Deadband	30.0%	(1.0 100.0)
	2182 Timer	60.0s	(10 300)
	2183 Output Relay A	R0	(R0 R3)
	2184 Output Relay B	R0	(R0 R3)

### 17.2.14 AVR regulation failure

The alarm is activated if the difference between the measured value and the set-point is outside the deadband for longer than the timer set-point.

2190	AVR Reg. Failure	SERVICE LEVEL	
	2191 Deadband	30.0%	(1.0 100.0)
	2192 Timer	60.0s	(10 300)
	2193 Output Relay A	R0	(R0 R3)
	2194 Output Relay B	R0	(R0 R3)

### 17.2.15 Breaker type

2200	Breaker T	уре	CUSTOMER LEVEL	
	2201	GB Туре	Pulse	(Pulse / Continuous)
	2202	МВ Туре	Pulse	(Pulse / Continuous)

If the selected type is 'pulse' then a closing pulse will be given for closing the breaker, and an opening pulse will be given to open the breaker.

When a contactor kit is used, then the selected type will be 'continuous'. Then a continuous signal will be given to the contactor when it needs to be closed, and the opening pulse output won't be used.

### 17.2.16 Static Synchronisation

With these parameters you can program the setpoint.

2210	Static S	Sync.	SERVICE LEVEL	
	2211	Df max.	0.1Hz	0.0 0.25)
	2212	DU max.	5%	(2 10)
	2213	Close Window	10.0 deg	(0.120.0)
	2214	KP	80	(0 1000)
	2215	KI	80	(0 1000)
	2216	Delay	1.0s	(0.0 5.0)

### 17.3 Power setup. Peak shaving operation

### 17.3.1 Mains power (import power)

The mains power set point is the maximum imported power from the mains. If the load is higher than this set point, the mains will supply the load equal to the mains power set point and the gen-set will supply all additional loads.

It is possible to have two set points, daytime and nighttime set point. The purpose of this is to adapt the mains import to the different load conditions in different periods.

The Qc4001 needs a 4...20mA signal on terminal 98-99 from an optional Power Transducer, measuring the imported power from the mains. The calibration of the Power Transducer must be:

### - 4 mA = 0.0 MW

- 20 mA = Transducer scale, set-point in channel 3013.

3010	Mains Power	CUSTOMER LEVEL	
	3011 Day	5000kW	(0 20000)
	3012 Night	5000kW	(0 20000)
	3013 Transducer Scale	5000kW	(0 20000)

### 17.3.2 Daytime period

The start / stop time of the daytime period are adjusted with hours and minutes. The period outside the daytime period is defined as the night time period.

3020	Daytime	Period	CUSTOMER L	_EVEL
	3021	Start Hour	8	(0 23)
	3022	Start Minute	0	(0 59)
	3023	Stop Hour	16	(0 23)
	3024	Stop Minute	0	(0 59)

### 17.3.3 Start gen-set

The set point is used to start the gen-set. When the imported mains power exceeds the setpoint in channel 3031, the gen-set is started and synchronised to the busbar. The set-point in channel 3031 is referring to the mains power set-points in channel 3011 or 3012. The start generator minimum load point is the minimum loading of the gen-set. The mains will always supply the maximum possible power. The additional power will be supplied by the gen-set.

Start Generator	CUSTOMER LEVEL	
3031 Setpoint	80%	(5 100)
3032 Delay	10.0s	(0.0 990.0)
3033 Minimum Load	10	(0 100)
	Start Generator3031Setpoint3032Delay3033Minimum Load	Start GeneratorCUSTOMER LEVEL3031Setpoint80%3032Delay10.0s3033Minimum Load10

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### 17.3.4 Stop gen-set

This set-point is used to stop the gen-set. When the imported mains power decreases below the set point the stop sequence of the genset is commenced. The set point in channel 3041 refers to the mains power set points in channel 3011 or 3012.

3040	Stop Generator		CUSTOMER LEVEL	
	3041	Setpoint	60%	(0 80)
	3042	Delay	600.0s	(0.0 990.0)

### 17.3.5 Load Dependent Start

With the option PMS this is the setpoint for setting the maximum load step needed in the application. The setpoint will tell you the minimal load step that always will be available by the gensets.

The delay is the time before the next unit will be started.

The minimum load is the setpoint on which the generator wants to run minimally in a peak shaving application.

3050	Load Dependent Start	CUSTOMER LEVEL	
	3051 Setpoint	50kW	(0 20000)
	3052 Delay	1.0s	(0.0 990.0)
	3053 Minimum Load	20kW	(0 20000)

# 17.3.6 Load Dependent Stop

With the option PMS the setpoint will give you the maximum power reserve before stopping the gensets

The delay is the time before the last genset will be stopped.

3060	Load Dependent Stop		CUSTOMER LEVEL	
	3061	Setpoint	100kW	(0 20000)
	3062	Delay	30.0s	(5.0 9900.0)

### 17.3.7 Test running

30	70	Te

Test		CUSTOMER LEVEL	
3071	Setpoint	50%	(1 100)
3072	Delay	300.0s	(30.0 990.0)
3073	Syncr.	OFF	(ON / OFF)

Test sequence:

When the TEST mode is selected, the gen-set is automatically started and synchronised with the mains. The sequence of the TEST is as follows:

- START sequence starts the gen-set
- Synchronise the generator breaker to the busbar (mains)
- Gen-set is loaded to the setting in channel 3071
- The parallel time expires and the generator is deloaded
- GB opens
- STOP sequence stops the gen-set

Pushing the TEST pushbutton on the display activates the test mode. The TEST mode can be used in peak shaving and AMF mode to check if the system is still functioning. After the test run the Qc4001 returns to AUTO mode.

If the setting 3073 (Syncr.) is OFF, the sequence of the test is as follows:

- START sequence starts the gen-set

- The test time expires and the STOP sequence stops the gen-set

17.3.8 Fixed power set-point (for active generator power and power factor)

The fixed power set points are used when the Qc4001 is configured to fixed power operation. The PF (power factor) set point is used when the generator is running parallel to mains.

3080	Fixed Power Setpoint		CUSTOMER LEVE	ïL
	3081	P Setpoint	80%	(0 100)
	3082	PF Setpoint	0.95	(0.60 1.00)

# 17.3.9 PMS Configuration

These are parameters that needs to be programmed if the option PMS is installed.

- The amount of generators that are installed in the application
- Activate the Qc4001 Mains controller in the application if needed.
- Activate the PMS in this Qc4001 controller.

### Warning:

By turning this parameter to ON in AUTO mode, the generator can start immediately. It is recommended to place the generator in SEMI-AUTO mode while programming the parameters !

- Program the Qc4001 command controller in the application. If one controller is set to ON the others will set automatically to OFF. Program the Qc4001 mains controller as command unit if possible. The command unit communicates the following parameters to the other connected units : start generator limit, start generator delay, stop generator limit, stop generator delay, command unit, start & stop command, timer values.
- Choose the way of starting up the application.

3100	PMS Configuration	CUSTOMER LEVEL	
	3101 # Gen-sets available	1	(1 16)
	3102 Mains available	OFF	(OFF / ON)
	3103 PMS active	OFF	(OFF / ON)
	3104 Command Unit	ON	(OFF / ON)
	3105 Enable Start/Stop	Local	(Remote / Local / Timer)

### 17.3.10 Internal Communication ID

Give every generator an individual ID. No duplicates are possible. Used only with the PMS option.

3110	Internal Communication ID	CUSTOMER LEVEL	
	3111 Intern. Comm. ID	1	(1 16)

# 17.3.11 Priority Select

Choose the priority in starting up the gensets either manually by ID-numbers of by the actual running hours.

Used only with the PMS option.

3120	Priority Select	CUSTOMER LEVEL	
	3121 Priority Select	Manual	(Manual / Running Hours)
Ma	anual = 0 / Running Hours = 1		

# 17.3.12 Number of ID's

Enable or disable every genset and mains controller in the PMS application. By disabling an ID, the generator won't be started but instead the next in the starting and stopping sequence.

Used only with the PMS option.

3130	Number	of ID's	CUSTOMER LE	VEL
	3131	Enable Mains	OFF	(OFF / ON)
	3132	Enable ID1	ON	(OFF / ON)
	3133	Enable ID2	OFF	(OFF / ON)
	3134	Enable ID3	OFF	(OFF / ON)
	3135	Enable ID4	OFF	(OFF / ON)
	3136	Enable ID5	OFF	(OFF / ON)

3140	Number	of ID's	CUSTOMER LEVE	EL
	3141	Enable ID6	OFF	(OFF / ON)
	3142	Enable ID7	OFF	(OFF / ON)
	3143	Enable ID8	OFF	(OFF / ON)
	3144	Enable ID9	OFF	(OFF / ON)
	3145	Enable ID10	OFF	(OFF / ON)
	3146	Enable ID11	OFF	(OFF / ON)

3150 Number of ID's

#### CUSTOMER LEVEL

3151	Enable ID12	OFF	(OFF / ON)
3152	Enable ID13	OFF	(OFF / ON)
3153	Enable ID14	OFF	(OFF / ON)
3154	Enable ID15	OFF	(OFF / ON)
3155	Enable ID16	OFF	(OFF / ON)

### 17.3.13 Priority of ID's

If manual priority (3120) is selected, the priority sequence needs to be programmed. Priority 1 means that the selected generator will be started first, then the generator with priority 2, etc.

Used only with the PMS option.

# 3160 Priority of ID's CUSTOMER LEVEL

3161	Priority ID1	1
3162	Priority ID2	2
3163	Priority ID3	3
3164	Priority ID4	4
3165	Priority ID5	5
3166	Transmit	OFF

(1 ... #Gen-sets Available)(1 ... #Gen-sets Available)(1 ... #Gen-sets Available)

(1 ... #Gen-sets Available)

(1 ... #Gen-sets Available) (OFF / ON)

#### 3170 Priority of ID's

Priority of ID's	CUSTOMER LEVEL	
3171 Priority ID6	6	(1 #Gen-sets Available)
3172 Priority ID7	7	(1 #Gen-sets Available)
3173 Priority ID8	8	(1 #Gen-sets Available)
3174 Priority ID9	9	(1 #Gen-sets Available)
3175 Priority ID10	10	(1 #Gen-sets Available)
3176 Priority ID11	11	(1 #Gen-sets Available)

ID's	CUSTOMER LEVEL	
Priority ID12	12	(1 #Gei
Priority ID13	13	(1 #Gei
Priority ID14	14	(1 #Gei
Priority ID15	15	(1 #Gei

#### 3180 Priority of

3181	Priority ID12	12	
3182	Priority ID13	13	
3183	Priority ID14	14	
3184	Priority ID15	15	
3185	Priority ID16	16	

n-sets Available) n-sets Available)

n-sets Available)

n-sets Available)

(1 ... #Gen-sets Available)

### 17.3.14 Running hours

If running hours priority (3120) is selected, this parameter will become available. The costumer can set the delay before running hours between the generators will be checked on which the priority is based on.

Used only with the PMS option.

3220	20 Running hours		COSTUMER LEVEL	
	3221	Hours	175	(120000)

### 17.3.15 Ground Relay

In some special multi-genset PMS applications it is necessary to connect only 1 Neutral at a time to the load. These relay outputs can be connected to the separate Neutral breaker for getting only 1 Neutral closed. This will be based on the priorities between the genset, the open&close signal of the GB and the running feedback of the gensets.

3230	Ground Relay	COSTUMER LEVEL	
	3231 Output Relay A	R0	(R0 R3)
	3232 Output Relay B	R0	(R0 R3)
	3233 Enable	OFF	(OFF / ON)

### 17.3.16 Stop Noncon. Gen-sets

Extra safety delay time to stop the generator when through PMS a stop command is given but after a certain amount of time the genset does not stop. Used only with the PMS option.

3240 Stop Noncon. Gen-sets COSTUMER LEVEL (10.0 ... 600.0) 3241 Delav 60.0s

### 17.3.17 Power Capacity

This parameter will only be available on the Qc4001 mains control unit and is used for programming the power capacity that is needed on the generator side before switching over. With a setpoint that is higher than the total available power capacity by the gensets, the Mains controller will not close the tie-breaker. Used only with the PMS option.

 3250
 Power Capacity
 COSTUMER LEVEL

 3251
 Power Capacity
 50kW
 (0...20000)

### 17.3.18 Tie breaker

This parameter will only be available on the Qc4001 mains control unit and is used for enabling the tie breaker.

Used only with the PMS option.

3260	Tie brea	ker	COSTUMER LEVEL	
	3261	Tie breaker	OFF	(OFF / ON)

### 17.4 System setup

In the system setup it is possible to set up the Qc4001 with the specific parameters for application, engine and generator.

# 17.4.1 Nominal settings (1<sup>st</sup> / 2<sup>nd</sup> / 3<sup>th</sup> / 4<sup>th</sup> Parameter Set)

The 1<sup>st</sup> parameter set is used as standard.

Depending on the input that is activated the other parameter sets will be used. On the QAC genn-sets 2 parameter sets will be used: the 1th set for 50Hz operation and the 2th set for 60Hz operation. The input is activated by the 50/60Hz switch on the cubicle.

4010	Nominal	Settings	SERVICE LEVEL	
	4011	Frequency	50Hz	(48.0 62.0)
	4012	Generator Power	720kW	(10 20000)
	4013	Generator Current	1300A	(0 9000)
	4014	Generator Voltage	400V	(100 25000)

4020	Nominal	Settings 2	SERVICE LEVEL		
	4021	Frequency	60Hz	(48.0 62.0)	
	4022	Generator Power	810kW	(10 20000)	
	4023	Generator Current	1217A	(0 9000)	
	4024	Generator Voltage	480V	(100 25000)	

4030	Nominal S	ettings 3	SERVICE LEVEL	
	4031	Frequency	50Hz	(48.0 62.0)
	4032	Generator Power	720kW	(10 20000)
	4033	Generator Current	1300A	(0 9000)
	4034	Generator Voltage	400V	(100 25000)
4040	Nominal S	ettings 4	SERVICE LEVEL	_
	4041	Frequency	50Hz	(48.0 62.0)
	4042	Generator Power	720kW	(10 20000)
	4043	Generator Current	1300A	(0 9000)
	4044	Generator Voltage	400V	(100 25000)

17.4.2 Transformer generator (for generator voltage measuring)

Voltage transformer: If no voltage transformer is present, the primary and secondary side values are set to generator nominal value.

4050	Transfo	rmer Gen.	SERVICE LEV	ÆL
	4051	Volt. Prim.	440V	(100 25000)
	4052	Volt. Sec.	440V	(100 690)
	4053	Current Prim.	1600A	(5 9000)
	4054	Current Sec.	5A	(1 / 5)

17.4.3 Transformer busbar (for busbar voltage measuring)

Voltage transformer: If no voltage transformer is present, the primary and secondary side values are set to generator nominal value.

4060	Transform	mer Bus	SERVICE LEVEL	
	4061	Volt. Prim.	440V	(100 25000)
	4062	Volt. Sec.	440V	(100 690)

### 17.4.4 External communication control (optional)

These setpoints will only be visible when an optional external communication extension card is mounted. The channels 4070-4094 are foreseen. The Baud rate can only be changed with Modbus communication.

### 17.4.5 Engine communication

4100	Engine Comr	ns.	SERVICE LEVEL		
	4101	Туре	DDEC		(OFF / MDEC / DDEC / EMR / JDEC)
0 = 0	OFF / 1 = MD	EC / 2 = DD	EC / 3 = EMR / 5 = JDEC	;	-

### NOTE: Selecting communication control ON will overrule external and internal settings.

### 17.4.6 Date and time (internal clock) setting

4110	Date and Time	e (internal clock)	CUSTOMER LEVEL	
	4110	Date	dd/mm/yyyy	( )
	4110	Time	Hh:mm	( )

17.4.7 Measuring of generator running time and circuit breaker operations

The function 'running time' counts the hours the generator has been running (voltage on generator present).

The function 'GB operations' counts how many times the generator breaker has been closed.

The function 'MB operations' counts how many times the mains breaker has been closed.

The counters can be reset/set.

# 4120 Counters

Counters				MASTE	R LEVEL	_	
	4121	Running Time		0		(0 20000)	)
	4122	GB Operations		0		(0 20000)	)
	4123	MB Operations		0		(0 20000)	)
	4124	Reset kWh		OFF			

### 17.4.8 Battery undervoltage / overvoltage alarm

4220	Battery L	ow	SERVICE LEVEL	
	4221	Setpoint	18.0V	(6.0 36.0)
	4222	Delay	3.0s	(0.0 999.0)
	4223	Output Relay A	R0	(R0 R3)
	4224	Output Relay B	R0	(R0 R3)
	4225	Enable	ON	(ON / OFF)

4230	Battery High		SERVICE LEVEL		
	4231	Setpoint	30.0V	(12.0 36.0)	
	4232	Delay	0.5s	(0.0 999.0)	
	4233	Output Relay A	R0	(R0 R3)	
	4234	Output Relay B	R0	(R0 R3)	
	4235	Enable	ON	(ON / OFF)	

### 17.4.9 Language

4240	Language	)	CUSTOMER LEVEL				
	4241	Language	English	(GB/NL/F/D/E/I/DK/S/N/SF/P)			
0 = Master / 1 = English / 2 = Danish / 3 = Dutch / 4 = Finnish / 5 = French / 6 = German /							
7 = Italian / 8 = Norwegian / 9 = Portuguese / 10 = Spanish / 11 = Swedish							

### 17.4.10 Loadshare output

This function enables the user to set the voltage level of the active power loadshare line. This is only possible if the loadshare type Pow-R-Con is chosen (channel 4250).

4250	Loadshare Out	CUSTOMER LEVEL	
	4251 Loadshare Out	5.0V	(1.0 5.0)

### 17.4.11 Loadshare type

This function enables the user to set the type of active power loadshare.

4260	Loadshare Type	CUSTOMER LEVEL	
	4261 Loadshare Type	Qc4001	(Qc4001 / Selco / Pow-R-Con)
0 =	= Qc4001 / 1 = Selco T4800 / 2		

### 17.4.12 Battery undervoltag / overvoltage alarm 2

4270	Battery Low 2		COSTUMER LEVEL	
	4271	Setpoint	N/A	(6.0 36.0)
	4272	Delay	10.0s	(0.0 999.0)
	4273	Output Relay A	R0	(R0 R3)
	4274	Output Relay B	R0	(R0 R3)
	4275	Enable	OFF	(ON / OFF)

4270	Battery High 2		COSTUMER LEVEL	_
	4281	Setpoint	N/A	(6.0 36.0)
	4282	Delay	0.5s	(0.0 999.0)
	4283	Output Relay A	R0	(R0 R3)
	4284	Output Relay B	R0	(R0 R3)
	4285	Enable	OFF	(ON / OFF)

### 17.4.13 Mode Relay

This function can be used to activate a relay in different modes.

4280	Mode Relay		COSTUM	COSTUMER LEVEL	
	4291	Test	R0		(R0 R3)
	4292	Auto	R0		(R0 R3)
	4293	Semi	R0		(R0 R3)
	4293	Semi	RU		(RU R3)

### 17.4.14 Engine type

4300	Engine	Туре	MASTER LEVEL	
	4301	Engine Type	Diesel	(Diesel / Gas)
0 :	= Diesel	/ 1 = Gas		

### 17.4.15 Gen-set modes

4320	Gen-Set Mode	CUSTOMER LEVEL	
	4321 Gen-Set Mode	Island	(Island / AMF / PS / FP / LTO / PMS)
0 =	= Island / 1 = AMF / 2 =	Peak Shaving / 3 = Fixed Power / 4 =	Load Take Over /
5 =	= Power Management	System	

### 17.4.16 CAN Unit

This parameter can be used to change the read-outs on the display.

4320	CAN Unit		CUSTOMER LEVEL		
	4331	CAN Unit	bar-celsius		(bar-celsius / psi-farenheit)
0	= bar-celsi				

### 17.4.17 Tacho configuration

4350	Tacho Config.		SERVICE LEVEL	
	4351	Setpoint	500rpm	(1 2000)
	4352	Teeth	0	(0 500)

The tacho input (=magnetic speed pick-up) must be configured to 0 teeth when not in use.

### 17.4.18 Start sequency of the engine

4360	Starter	COSTUMER LEVEL	_
	4361 Start Prepare	1.0s	(0.0 600.0)
	4362 Start ON Time	12.0s	(1.0 30.0)
	4363 Start OFF Time	12.0s	(1.0 99.0)
	4364 Prepare	Normal	(Normal/ Extended)
4370	Start Attempts	SERVICE LEVEL	
	4371 Attempts	3	(1 10)
	4372 Output Relay A	R0	(R0 R3)
	4373 Output Relay B	R0	(R0 R3)

The settings "start prepare", "start ON time" and "start OFF time" are the periods that the relays on the engine interface card slot #7 are activated.

The start prepare output can for example be used for prelubricating or preheating. The start relay output is for activating the starter of the engine and the stop relay output is for activating the engine.

The amount of start attempts can be defined.

The start sequence is interrupted in the following situations:

- Running feedback from the engine
- Voltage is present at the generator
- STOP signal, e.g. by STOP pushbutton in SEMI-AUTO
- Shutdown alarm

The interruption deactivates the start relay, and a start failure alarm is displayed.

# 17.4.19 GB ON / GB OFF sequence

The GB ON sequence will synchronise and/or close the generator breaker. The breaker is closed directly without synchronising if the mains breaker is open or if no mains breaker is present (island mode), this means if the voltage on the busbar/mains is not present. The GB ON sequence is automatically initiated (except in SEMI-AUTO mode) when the automatic start sequence has been completed and the engine is running. In SEMI-AUTO mode the operator may initiate the GB ON sequence by pressing the "GB" pushbutton on the display.

Conditions, which must be fulfilled before a GB ON signal is activated:

- Running feedback from the engine (channel 4351, tacho configuration set-point or running feedback input).
- The frequency and voltage has been present in the time "f/U OK" (channel 4381).

This will initiate synchronising and/or closing of the generator breaker.

f/U OK		SERVICE LEVEL	
4381	Delay	3.0s	(1.0 99.0)
f/U failure	)	SERVICE LEVEL	
4391	Delay	30.0s	(1.0 99.0)
4392	Output Relay A	R0	(R0 R3)
4393	Output Relay B	R0	(R0 R3)
	f/U OK 4381 f/U failure 4391 4392 4393	f/U OK 4381 Delay f/U failure 4391 Delay 4392 Output Relay A 4393 Output Relay B	f/U OK         SERVICE LEVEL           4381         Delay         3.0s           f/U failure         SERVICE LEVEL           4391         Delay         30.0s           4392         Output Relay A         R0           4393         Output Relay B         R0

The GB ON sequence is interrupted when:

- Synchronisation alarm
- GB ON alarm
- GB pushbutton pressed in SEMI-AUTO mode
- f/U failure

The GB OFF sequence is automatically initiated (except in SEMI-AUTO mode) when the generator has to be stopped. In AMF operation this is when the mains returns and the mains breaker is synchronised, and in PEAK SHAVING and LOAD TAKE OVER operation this is when the load is to be supplied by the mains only.

In SEMI-AUTO mode the operator may initiate the GB OFF sequence by pressing the "GB" pushbutton on the display.

Sequence (if parallel with mains):

- De-load the generator
- Open the breaker at a configurable setpoint (channel 2122)

Sequence (if island mode):

- Open the breaker immediately

The GB OFF sequence is interrupted when:

- A DELOAD alarm
- A GB OFFalarm
- GB pushbutton is pressed in SEMI-AUTO mode

17.4.20 MB ON / MB OFF sequence

The MB ON sequence will synchronise and/or close the mains breaker.

In AUTO mode the MB ON sequence is automatically initiated if the Qc4001 is in AMF operation and the mains returns after a mains failure. In peak shaving mode the MB ON sequence is automatically initiated when the mains is OK.

If the generator breaker is open and the mains is present, the MB will be closed immediately in AUTO mode.

In SEMI-AUTO mode the operator may initiate the MB ON sequence by pressing the "MB" pushbutton on the display. Pressing the MB pushbutton in SEMI-AUTO will close the MB immediately, if the GB is open and the mains is present.

Conditions that must be fulfilled before a MB ON signal is activated:

- No active MB alarms
- Mains OK

This will initiate synchronising and/or closing of the mains breaker.

Interruption of the MB ON sequence:

- Mains failure alarm
- MB ON alarm
- MB OFF pushbutton in SEMI-AUTO.

The MB OFF sequence is automatically initiated (except in SEMI-AUTO mode). In SEMI-AUTO mode the operator may initiate the MB OFF sequence by pressing the "MB" pushbutton on the display.

Sequence: AUTO (mains failure)

- Mains not present
- Open the mains breaker

Sequence: SEMI-AUTO (gen-set parallel with mains)

- MB pushbutton is pressed
- Open the mains breaker

Sequence: SEMI-AUTO (gen-set stopped, the mains supplies the load)

- MB OFF pushbutton pressed
- Open the mains breaker

Interruption of the MB OFF sequence:

- MB OFF alarm
- Pressing the MB pushbutton in SEMI-AUTO operation

17.4.21 Stop sequence

Stop sequence:

- Programmable cooling down time
- "STOP" output with programmable extended stop time

The stop sequence is carried out when the Qc4001 has completed the GB OFF sequence and the generator breaker is open.

In AUTO mode the stop sequence is initiated automatically. In SEMI-AUTO mode a stop command with the "STOP" pushbutton will stop the engine without cooling down. If the generator is running with the generator breaker closed and the "STOP" pushbutton is pressed, the generator is opened without deloading, and the engine is stopped without cooling down.

A start command will interrupt an ongoing cool down period and leave the engine in idle speed. A GB ON signal will synchronise and close the breaker.

A stop failure is displayed if the running feedback signal or the generator voltage and frequency are still present.

If the coil type is configured as 'running coil', the stop coil will be energized during starting and running and de-energized during stopping.

**STOP** parameters

4400	Stop		SERVICE LEVEL	
	4401	1 Cool Down Time	60.0s	(0.0 990.0)
	4402	2 Extended Stop	15.0s	(1.0 99.0)
	4403	3 Coil Type	RUN	(RUN / STOP)
0	= Run (	Coil / 1 = Stop Coil		
4410 \$	Stop Fa	ilure	SERVICE LEVEL	
	4411	Delay	20.0s	(10.0 120.0)
	4412	Output Relay A	R0	(R0 R3)
	4413	Output Relay B	R0	(R0 R3)

Mains failure:

Automatic mains failure is detected when the Qc4001 is in AUTO mode and configured as an AMF unit. When the timer "FAIL DELAY" expires the following sequence is carried out: - MB is opened

- Start sequence is initiated
- GB is closed

In case of MB open fail the sequence is stopped and an "MB OPEN FAILURE" alarm is displayed.

When the mains returns the change-over sequence is started. The sequence is started when the timer "MAINS OK DELAY" expires:

- MB is synchronised
- GB is de-loaded (if parallel running is allowed)
- GB is opened
- Stop sequence is initiated

In case of a sequence alarm the sequence will be stopped. If GB OFF fail and parallel running is not allowed, then the MB is opened.

4420	Mains V Failure	CUSTOMER LEVEL	
	4421 Fail Delay	1.0s	(1.0 990.0)
	4422 Mains OK Delay	60.0s	(10.0 990.0)
	4423 Low Voltage	75%	(50 100)
	4424 High Voltage	120%	(100 150)
	4425 Mains Fail Control	Start+Open MB	(Start / Start+Open MB)
0	= Start+Open MB / 1 = Start		
4430 <u>N</u>	Aains Hz Failure	CUSTOMER LEVEL	
	4431 Fail Delay	1.0s	(1.0 990.0)
	4432 Mains OK Delay	60.0s	(10.0 990.0)
	4433 Low Frequency	95%	(80 100)
	4434 High Frequency	105%	(100 120)

### 17.4.22 MB Control

4440 <u>N</u>	IB Contr	rol	SERVICE LEVEL	
	4441	Function	Mode Shift OFF	(MS OFF / PS-AMF-PS / LTO-AMF-LTO)
	4442	Timer	0.5s	(0.0 30.0)
	4443	Back Sync.	OFF	(ON / OFF)
	4444	Synchr. Timer	75ms	(40 3000)

Description of Mode Shift:

In case of Peak Shaving, Fixed Power and Load Take Over mode, it is possible to enable the AMF function as a second application, next to the chosen mode.

If then a mains failure occurs, the unit changes to AMF operation and finally it returns to the chosen mode when the mains supply is restored.

### 17.4.23 Horn timeout

4450	Alarm Horn		CUSTOMER LEVEL	
	4451	Delay	20.0s	(0.0 990.0)

The setting is the maximum time the horn is sounding at an alarm. If the setting is adjusted to 0 s, the horn will sound continuously until the alarm is acknowledged.

### 17.4.24 GB Control

4460	GB Control	CUSTOMER LEVEL	
	4461 GB Close Delay	1.0s	(0.0 30.0)

17.4.25 Analogue output configuration (optional)

The analogue output option consists of two independent 0/4...20mA outputs. The related setpoints will only be shown when this analogue output extension card is mounted.

### 17.4.26 Relay Setup

The relays can be configured in the 2 different ways described below.

Alarm Relay Function:When an alarm activates the relay, it is activated as long as<br/>the alarm is present and unacknowledged.Limit Function:When an alarm activates the relay, no alarm message is<br/>displayed. After that the condition which activates this relay<br/>has returned to normal, the relay will deactivate after the<br/>'Off Delay' has expired.

4610	Relay 1		SERVICE LEVEL	
	4611	Function	Alarm	(Limit / Alarm)
	4612	Off Delay	0.0s	(0.0 999.9)
4620	Relay 2		SERVICE LEVEL	
	4621	Function	Alarm	(Limit / Alarm)
	4622	Off Delay	0.0s	(0.0 999.9)
4630	Relay 3		SERVICE LEVEL	
	4631	Function	Alarm	(Limit / Alarm)
	4632	Off Delay	0.0s	(0.0 999.9)
4640	Relay 4		SERVICE LEVEL	
	4641	Function	Alarm	(Limit / Alarm)
	4642	Off Delay	0.0s	(0.0 999.9)

17.4.27 Relay Setup (optional)

These setpoints will only be shown when the optional output relay extension card is mounted in the Qc4001. The channels 4650-4682 are foreseen.

17.4.28 Real Time Clock Start & Stop commands

Up to 8 start/stop commands can be programmed on a weekly base.

These commands, if enabled, can be used when the Qc4001 is in AUTO-mode in following applications:

- Island Mode
- Fixed Power Mode
- Load Take Over Mode

If a Start command is enabled, then a Stop command should be enabled as well. Else the genset will keep on running.

For example: in channel 4710 a Start command can be defined on Monday 10h00, and in channel 4720 a Stop command can be defined on Tuesday 14h00.

Following days or groups of days can be selected:

Setting				
MO	0			
TU	1			
WE	2			
TH	3			
FR	4			
SA	5			
SU	6			
MO-TU-WE-TH	7			
MO-TU-WE-TH-				
FR	8			
SA-SU	9			
MO-TU-WE-TH-				
FR -SA-SU	10			

4710 Start/Stop Cmd. 1

#### CUSTOMER LEVEL

4711	Enable	OFF	(0
4712	START/STOP	STOP	(S
4713	Day(s)	10	(0
4714	Hour	10	(0
4715	Minute	0	(0

(ON / OFF) (START / STOP) (0 / 1 / 2 / 3 / 4 / 5 / 6 / 7 / 8 / 9 / 10) (0 ... 23) (0 ... 59)

4720 Start/Stop Cmd. 2

CUSTOMER LEVEL

4721	Enable	OFF	((
4722	START/STOP	STOP	(.
4723	Day(s)	11	((
4724	Hour	10	((
4725	Minute	0	((

ON / OFF) START / STOP) 0 / 1 / 2 / 3 / 4 / 5 / 6 / 7 / 8 / 9 / 10) 0 ... 23) 0 ... 59)

#### 4730 Start/Stop Cmd. 3

4740

#### CUSTOMER LEVEL

4731	Enable	OFF
4732	START/STOP	STOP
4733	Day(s)	11
4734	Hour	10
4735	Minute	0

(ON / OFF) (START / STOP) (0 / 1 / 2 / 3 / 4 / 5 / 6 / 7 / 8 / 9 / 10) (0 ... 23) (0 ... 59)

#### Start/Stop Cmd. 4 CUSTOMER LEVEL

4741	Enable	OFF	(0
4742	START/STOP	STOP	(S
4743	Day(s)	11	(0
4744	Hour	10	(0
4745	Minute	0	(0

ON/OFF) START/STOP) D/1 /2/3/4/5/6/7/8/9/10) D.... 23) D.... 59)

#### 4750 Start/Stop Cmd. 5

4751	Enable	OFF	()
4752	START/STOP	STOP	(.
4753	Day(s)	11	((
4754	Hour	10	((
4755	Minute	0	((

′ON / OFF) ′START / STOP) ′0 / 1 / 2 / 3 / 4 / 5 / 6 / 7 / 8 / 9 / 10) ′0 ... 23) ′0 ... 59)

#### 4760 Start/Stop Cmd. 6 C

#### **CUSTOMER LEVEL**

**CUSTOMER LEVEL** 

4761	Enable	OFF	
4762	START/STOP	STOP	
4763	Day(s)	11	
4764	Hour	10	
4765	Minute	0	

(ON / OFF) (START / STOP) (0 / 1 / 2 / 3 / 4 / 5 / 6 / 7 / 8 / 9 / 10) (0 ... 23) (0 ... 59)

#### 4770 Start/Stop Cmd. 7

#### CUSTOMER LEVEL

4771	Enable	OFF	(0)
4772	START/STOP	STOP	(S7
4773	Day(s)	11	(0)
4774	Hour	10	(0.
4775	Minute	0	(0.

′ON / OFF) ′START / STOP) ′0 / 1 / 2 / 3 / 4 / 5 / 6 / 7 / 8 / 9 / 10) ′0 ... 23) ′0 ... 59)

#### 4780 Start/Stop Cmd. 8

#### CUSTOMER LEVEL

4781	Enable	OFF
4782	START/STOP	STOP
4783	Day(s)	11
4784	Hour	10
4785	Minute	0
Ctart / 1 -	Cton	

(ON / OFF) (START / STOP) (0 / 1 / 2 / 3 / 4 / 5 / 6 / 7 / 8 / 9 / 10) (0 ... 23) (0 ... 59)

0 = Start / 1 = Stop

### 17.4.29 GSM Pin Code

4790	GSM Pin	Code	COSTUMER LEVEL	
	4791	Pin code	0000	(0 9999)

### 17.4.30 Service Time

Two maintenance intervals can be monitored.

Both monitor the running hours (with a counter) and the elapsed time (with a timer) since the last service. The first parameter (counter or timer) that reaches its defined limit, will give a maintenance warning to the user.

For example on a QIX gen-set the maintenance interval is 500 running hours or 1 year, whichever comes first.

For each of the two intervals, if either the setted running hours or the setted elapsed time is reached, an alarm will be given.

Each interval can be reset by enabling the reset function. Then the respectively counter and timer will be put to 0.

The Service Timer menus can only be entered using the "JUMP" pushbutton.

4910	Service T	imer 1	SERVICE LEVEL	
	4911	Enable	ON	(ON / OFF)
	4912	Run Hours	500h	(10 10000)
	4913	Elapsed Time	365 days	(1 1000)
	4914	Fail Class	Warning	(Warning / Trip / Trip+Stop / Shutdown)
	4915	Output Relay A	R0	(R0 R3)
	4916	Reset		

#### 4920 Service Timer 2

SERVICE LEVEL 4921 Enable ON 4922 Run Hours 1000h 4923 Elapsed Time 365 days 4924 Fail Class Warning **Output Relay A** R0 4925 4926 Reset

(ON / OFF) (10 ... 10000) (1 ... 1000) (Warning / Trip / Trip+Stop / Shutdown) (R0 ... R3)

### 17.4.31 Diagnostic Mode

4930	1930 Diagnostics Mode		CUSTOMER LEVEL	
	4930	Diagnostics	Normal	(Normal / Diagnostics)
0 =	= Normal /	1 = Diagnostics		

### 17.4.32 User passwords

4940	Reset Event	log	MASTER LEVEL	
	4940	Reset	OFF	(ON / OFF)

### 17.4.33 User passwords

Only the level 1 (customer level) password can be changed through the display menu. Higher levels of passwords can only be changed through theQc4001 Utility Software.

The level 1 password menu can only be entered using the "JUMP" pushbutton.

4971	Level 1 Pas	sword	CUSTOMER LEVEL	
	4971	Setting	2003	(0 32000)
4972	Level 2 Pas	sword	SERVICE LEVEL	
	4972	Setting	****	(0 32000)
4973	Level 3 Pas	sword	MASTER LEVEL	
	4973	Setting	****	(0 32000)

### 17.4.34 Service menu

The service menu can only be entered using the "JUMP" pushbutton. This menu is used in service situations.

In the alarm selection you can see all the alarm timers and their remaining time if they are counting.

The input and output selections show the present status of the inputs and outputs. E.g. mode inputs, relay outputs and load sharing lines.

No.	Se	tting	Description
4980	Service Menu	Selection Display	
4981	Service Menu	Alarm	Shows remaining alarm delay time
4982	Service Menu	Digital Inputs	Shows digital input status
4983	Service Menu	Digital Outputs	Shows digital output status

### 17.4.35 Diagnostics menu

This diagnostics menu can only be entered using the "JUMP" pushbutton. This menu is used in (mainly EMR) diagnostics situations.

If diagnostics is selected in this menu, the fuel solenoid relay output will be de-energized for 30 seconds (to make sure that the unit is completely stopped), and then gets energized again. Then EMR diagnostics can take place.

To leave this status, normal operation has to be selected again in this menu.

4930	30 Diagnostics Mode		CUSTOMER LEVEL	
	4930	Diagnostics	Normal	(Normal / Diagnostics)

### It's only possible to start the gen-set when this parameter is at 'Normal'.

### 17.4.36 Clear Log Menu

This menu can only be entered by using the "JUMP" pushbutton. This menu will be used when the gen-sets leave the Atlas Copco test area, to clear the log memory in the Qc4001.

4940	Reset Eventlog		MASTER	
	4940	Reset	OFF	(ON / OFF)

### 17.4.37 Parameter Set ID

This is a text field which is saved and loaded together with the parameter set. The text is editable and contain a maximum of 15 characters (can be a combination of all kind of characters, eg. '9822 0999 97\_02').

This text is listed in the 'parameters shown on the display 'list.

This text can only be entered or edited through the Utility Software in the parameter file

# 17.4.38 Application

This parameter is default set on 0; only in a PMS application the Qc4001 mains controller needs to be set at 1.

Used only with the PMS option.

Warning : If a genset Qc4001 controller is set at 1; all the settings will be lost !

5000	Application		MASTER	_
	5000	Application	0	(0 / 1)

### 17.4.39 VDO 1

Parameters to be programmed when a configurable oil pressure sensor is used.

5010	VDO 1		SERVICE LEVEL	
	5011	VDO 1 @ 0,0 bar	10	(0 240)
	5012	VDO 1 @ 2,5 bar	44,9	(0 240)
	5013	VDO 1 @ 5,0 bar	81	(0 240)
	5014	VDO 1 @ 6,0 bar	134,7	(0 240)

5020	VDO 1		SERVICE LEVEL	
	5021	VDO 1 @ 7,0 bar	184	(0 240)
	5022	VDO 1 @ 8,0 bar	200	(0 240)
	5023	VDO 1 @ 9,0 bar	210	(0 240)
	5024	VDO 1 @ 10,0 bar	220	(0 240)

### 17.4.40 VDO 2

Parameters to be programmed when a configurable coolant temperature sensor is used.

5030	VDO 2		SERVICE LEVEL	
	5031	VDO 2 @ 40 °C	292	(0 480)
	5032	VDO 2 @ 50 °C	197	(0 480)
	5033	VDO 2 @ 60 °C	134	(0 480)
	5034	VDO 2 @ 70 °C	97	(0 480)

#### 5040 VDO 2

VDO 2		SERVICE LEVEL	
5041	VDO 2 @ 80 °C	70	(0 480)
5042	VDO 2 @ 90 °C	51	(0 480)
5043	VDO 2 @ 100 °C	39	(0 480)
5044	VDO 2 @ 110 °C	29	(0 480)

### 17.4.41 VDO 3

Parameters to be programmed when a configurable fuel level sensor is used.

5050	VDO 3		SERVICE LEVEL	
	5051	VDO 3 @ 0%	78,8	(0 180)
	5052	VDO 3 @ 40%	47,9	(0 180)
	5053	VDO 3 @ 50%	40,2	(0 180)
	5054	VDO 3 @ 60%	32,5	(0 180)
5060	VDO 3		SERVICE LEVEL	_
	5061	VDO 3 @ 70%	24,8	(0 180)
	5062	VDO 3 @ 80%	17	(0 180)
	5063	VDO 3 @ 90%	9,3	(0 180)

1,6

5064 VDO 3 @ 100%

(0 ... 180)
### 18 <u>Technical specifications</u>

Accuracy: Class 1.0 according to IEC 688.

Operating temperature: -25...70 °C.

Aux. supply: 12/24 VDC -25/+30 %. Guaranteed performance @ dips down to 6V (for max. 1s.) during starting.

Measuring voltage: 100...690 VAC. Consumption max. 0.15 VA per phase.

Frequency: 30...70 Hz.

Measuring current: From current transformers .../1 A or .../5 A. Consumption max. 0.3 VA per phase.

Binary inputs: Input voltage 6...32 VDC. Impedance 2.4 k ., bi-directional.

Open collector outputs: Supply voltage 6...32 VDC. Load max. 10 mA.

Load sharing lines: +/-5 VDC.

Analogue inputs: +/-10 VDC, impedance 100 k .(not galvanically separated).

Relay outputs: 250 V/8 A or 24 VDC/1 A. Refer to actual description of I/O's.

Safety: To EN 61010-1 installation category (overvoltage category) III, 600 V, pollution degree 2.

CE and C-UL approved.

Galvanic separation: Between AC voltage, AC current and other I/O's: 3250 VAC - 50 Hz - 1 min. Between analogue outputs: 500 VDC - 1 min.

EMC/CE: According to EN-50081-1/2, EN-50082-1/2, SS4361503 (PL4) and IEC 255-3.

Material: All plastic parts are self-extinguishing to UL94 (V1).

Climate: HSE, to DIN 40040.

Connections: 4 mm<sup>2</sup> multi stranded for AC currents, all others 2.5 mm<sup>2</sup> multi stranded.

Response times: From the set-point is reached till the output is activated and the delay set to 0.

Generator: Over/under voltage 70-200 ms. Over/under frequency 70-200 ms.

Current: 100-200 ms. Fast overcurrent: <42 ms. High overcurrent: 100-200 ms.

Rocof: 100 ms (4 periods).

Vector jump: 30 ms.

Protection: Case: IP40.

Terminals: IP20.

Operator panel: IP52.

To IEC 529 and EN 60529.

Mounting: Base mounted with six screws or DIN-rail mounted.

Protection of PCB's: all PCB's shall be sprayed to guarantee good functioning of the controller in humid environments.

Cold Tested according to IEC 68-2-1.

Dry Heat Tested according to IEC 68-2-2.

Damp Heat Dynamic Tested according IEC 68-2-30.

Vibration Tested according IEC 60068-2-6.

Shock Tested according IEC 68-2-27.

Flammability Test according to IEC 695-2-2.

# 19 Dimensions

### 19.1 Unit dimensions



### 19.2 Display Dimensions



#### 19.3 Panel cutout for display



## 20 Engine Communication CAN-bus

#### 20.1 MTU MDEC

Specifications: All necessary information and specifications about the MDEC CAN-bus can be found in following MTU manuals:

- 'Connecting third-party devices to the MCS-5 FIELD BUS 1 / Documentation for design engineers / Structure and function of the field bus 1 communication protocol' E 531 827 / 00 E
- 'CAN bus interface / MTU-MDEC to third-party systems / DDC-MTU Series 2000 / Stationary applications / Documentation Part 1' E 531 966 / 00 E

MDEC Messages displayed on the Qc4001:

Object	Туре
Engine Speed	Value
Overspeed Shutdown	Shutdown
MDEC Yellow Alarm	Warning
MDEC Red Alarm	Shutdown
Oil Pressure	Value
Low Oil Pressure Warning	Warning
Low Oil Pressure Shutdown	Shutdown
Charge Air Pressure	Value
Low Coolant Level Warning	Warning
Actual MDEC Failures	Digits
MDEC ECU Failure	Shutdown
Coolant Temperature	Value
High Coolant Temp. Warning	Warning
High Coolant Temp. Shutdown	Shutdown
Charge Air Temperature	Value
High Intercooler Temp.	Warning
Oil Temperature	Value
High Oil Temp. Shutdown	Shutdown
Fuel Temperature	Value
High Charge Air Temp. Shutdown	Shutdown
Defect Coolant Level Switch	Warning
Intercooler Temperature	Value

#### 20.2 Deutz EMR

Specifications: All necessary information and specification about the EMR CAN-bus can be found in following Deutz manual:

- 'EMR CAN Messages Documentation V1'

EMR Messages displayed on the Qc4001

Object	Туре
High Coolant Temp. Shutdown	Shutdown
Low Oil Pressure Shutdown	Shutdown
Overspeed Shutdown	Shutdown
EMR Warning	Warning
EMR Shutdown	Shutdown
Actual EMR Faults	Digits
Coolant Temperature	Value
Oil Pressure	Value
Engine Speed	Value

#### 20.3 Detroit Diesel DDEC IV

Specifications: All necessary information and specification about the DDEC IV CAN-bus can be found in the following Detroit Diesel manual:

- 'Detroit Diesel DDEC IV Application and Installation Manual' in Chapter 5 'Communication Protocols'.

DDEC IV Messages displayed on the Qc4001:

Object	Туре
Engine Speed	Value
Coolant Temperature	Value
Engine Oil Temperature	Value
Fuel Temperature	Value
Engine Oil Pressure	Value
Coolant Level	Value
Fuel Rate	Value
Air Inlet Temperature	Value
Boost Pressure	Value